

LENS DESIGN USING HYBRID CODED NSGA2

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OUTLINE

- LENS DESIGN FUNDAMENTALS
- TRIPLET DESIGN PROBLEM.
- WHY GA?
- WHY MULTI-OBJECTIVE GA?
- WHAT IS HYBRID CODING?
- WHY HYBRID CODING?
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LENS DESIGN FUNDAMENTALS

- Optical System Optimization
 - Aberrations
 - Definition of Objective Functions or Merit Functions.
 - Definition of Constructional Parameters.
 - Linear Algebra based formulation of Merit Function.
- Ray Tracing
- Traditional Single Objective Optimization Procedure
- Proposed Multi-Objective Optimization Procedure.

ABERRATIONS

- Aberrations are the representations of deviations from linear correspondence between an object and its image.
- In ray optics, we have aberrations in our system, if a unique point in object space does not map to a unique point in image space linearly. In wave optics, if we have a spherical incident wave front and a non spherical outgoing wave front for an optical system, we have aberrations present.
- Aberrations are classified in such a way that we can visually identify them while still making them orthogonal to each other. It is the shape of the ray fan plots and spot diagrams that help us identify the aberrations.
- A ray fan plot is the value of Transverse Ray Aberration (TRA) plotted as a function of normalized radial distance on pupil.
- TRA is the distance between the ideal image point and the actual image point on the chosen image plane in the transverse direction.
- We obtain ray fan plots by letting the rays from an off axis point incident along a single line in the pupil.
- Spot diagrams are obtained by uniformly illuminating a pupil in two dimensions by rays originating from a single object point. The distribution of ray pierces on the image plane can help us identify various aberrations.

ABERRATIONS (continued)

- The wave front aberrations are considered when the aberration effects in the system are closer to the diffraction limited performance.
- For each point in the exit pupil (x, y), we describe the optical path difference W (x, y) between the aberrated wave front and the spherical reference surface. We can describe W either using Seidel polynomials as done in Optical design or using Zernike polynomials as done during the optical testing. Using Seidel polynomials [see Geary] we can write,

$$W = \sum_{i,j,k} W_{ijk} \bar{H}^i \rho^j \cos^k \phi$$

- Here, the four terms in the expansion above are the wave front aberration coefficient, fractional image height; normalized pupil radius ($\rho = \frac{y}{r}$) and the cosine of the other pupil coordinate in the given order.
- The distance between the exit pupil and the paraxial plane is R. The Transverse ray aberration can be calculated from W by using

$$T = -\left(\frac{R}{r}\right) \frac{dW}{d\rho}$$

MERIT FUNCTION & CONSTRUCTIONAL PARAMETERS

- An optical system will have a number of constructional parameters which specify the system. These include the radius of curvatures of the lens elements, the distance between various surfaces, position of stops etc. Let the system be having M aberrations defined over a space of N constructional parameters. The symbols and definitions used are those used by **Vasiljevic**.
- The merit function is defined by

$$\Phi = \sum_{i=1}^M f_i^2(x_1, x_2, \dots, x_N)$$

- Where f are the aberrations and X is a vector of constructional parameters and

$$X = (x_1, x_2, \dots, x_N)$$

refers to a point in the parameter space. There can be a number of equality and inequality constraints imposed among the constructional parameters.

LINEAR ALGEBRA BASED FORMULATION OF MERIT FUNCTION

$$X = -(A^T \cdot A)^{-1} \cdot A^T \cdot F_0$$

- where F denote the vector containing the aberration functions which are functions of the constructional parameters. The matrix A with elements a_{ij} is defined as the first partial derivative of f_i with respect to x_j
- The above formulation is for a single objective optimization.
- **The difference when we have multiple objectives is to have different F vectors for different objectives. But the relevant "aberrations" to include might have to be rewritten according to the metric defined for each objective. Hence the A vector and F vectors will be different with different dimensions corresponding to the nature of the objective.**

RAY TRACING

- Snell's Law is the fundamental equation for Ray Tracing.
- Optical Design Software CODE V® was employed to do the ray tracing. Ray tracing and evaluation gives us values for the required objective functions.
- CODE V® interacts with NSGA2 written in C through the COM interface of Visual Studio. (This interface is very slow.)

TRADITIONAL SINGLE OBJECTIVE OPTIMIZATION PROCEDURE

- First order lay out based on paraxial (Gaussian) approximation.
- Based on Optical Engineering insight, form a Merit Function (Objective Function) for the required performance criteria. Here the experience of the designer DOES MATTER.
- Optimize the Merit function. Try different local optimization techniques.
- Try different starting points.
- Try various global optimization techniques.
- Analyze the results for manufacturability. Conduct a Tolerance Analysis.

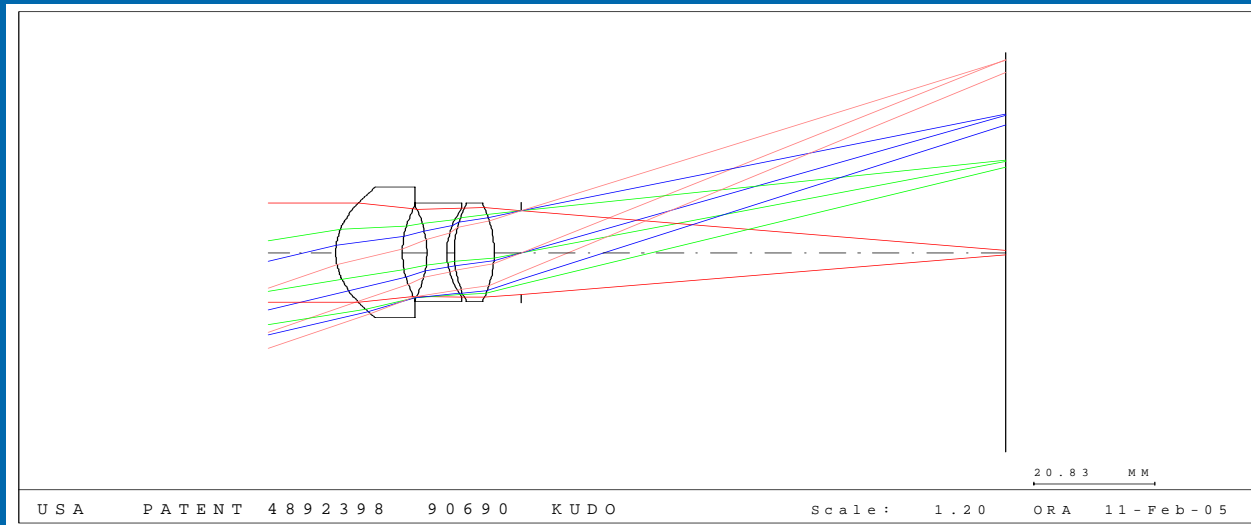
PROPOSED MULTI-OBJECTIVE OPTIMIZATION PROCEDURE

- Choose Multiple Merit functions consistent with the performance requirement.
- Optimize using Multi-Objective Evolutionary Algorithms.
- Use these solutions as a starting point and conduct Single Objective local and global Optimization for suitably chosen Merit function.
- Analyze for manufacturability. Conduct Tolerance Analysis.
- The following Improvements are anticipated.
 - Reduced dependence on Optical Engineering insight in choosing suitable starting points and Merit function.
 - Obtain multiple and Diverse Pareto-Optimal Solutions in a single run.
 - Obtain multiple manufacturing choices for a given performance.

TRIplet DESIGN PROBLEM

- Minimize Seidel Aberration Coefficients corresponding to Spherical Aberration (SA) and Distortion (DST).
- Obtain Diverse Pareto-Optimal Solutions.
- Use them as a set of Diverse starting points for Single Objective Local and Global Optimizations. (Selection of proper starting point is usually difficult). Here the Default Merit Function from CODE V® is used.

ORIGINAL DESIGN



This is the ORIGINAL DESIGN chosen from Patent Literature. We would like to improve up on our two objectives, minimization of coefficients of Spherical Aberration (SA) and Distortion (DST). There are 13 variables. They are 6 radii, 3 glass thickness, 2 air gaps, 1 distance from the last glass surface to the stop, distance between the paraxial image and real image.

ABERRATION COEFFICIENTS AND FIRST ORDER QUANTITIES FOR THE ORIGINAL

THO SO.J

USA PATENT 4892398 90690 KUDO

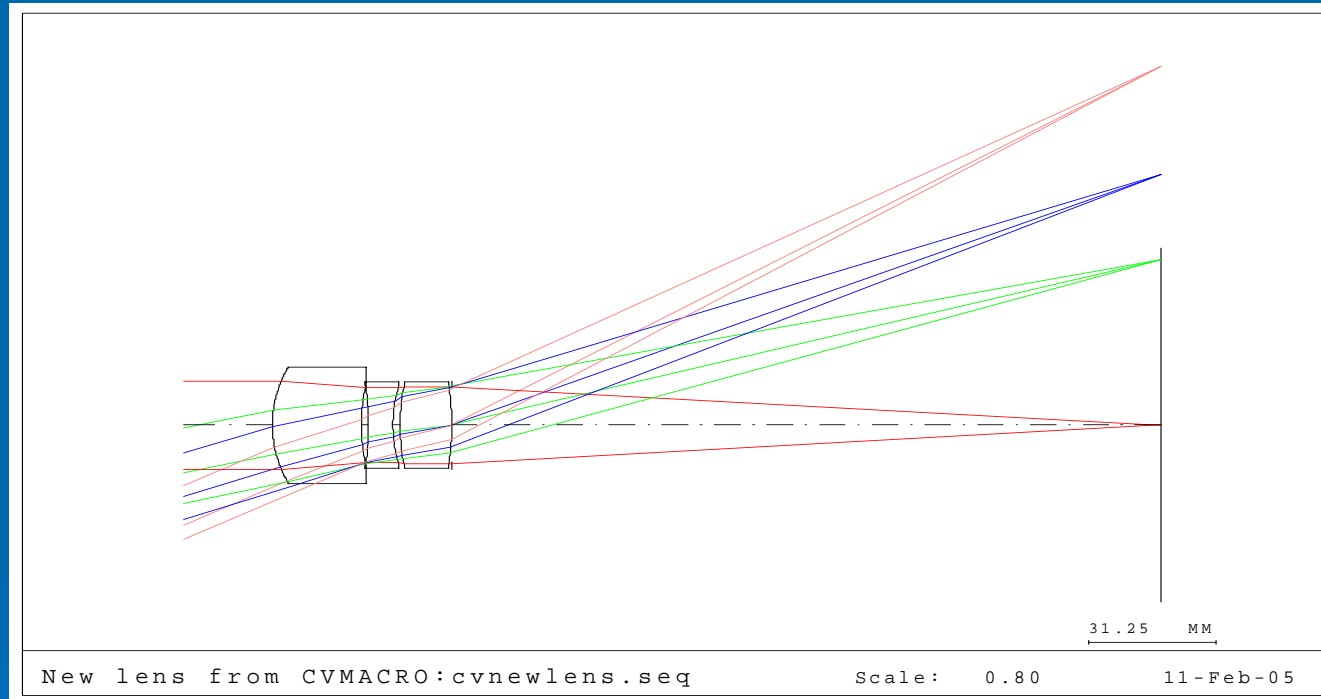
Position 1, Wavelength = 587.6 NM

	SA	TCO	TAS	SAS	PTB	DST	AX	LAT	PTZ
1	-1.390593	0.360706	-2.783492	-2.762700	-2.752304	0.238872	-0.447814	0.038720	-0.011528
	0.033922	-0.126032	0.156085	0.052028		-0.064435	ASPHERIC CONTRIBUTIONS		
2	0.008142	0.067503	2.003355	1.878991	1.816810	5.192648	0.141447	0.390892	0.007610
3	0.679764	-5.201052	15.155950	6.312706	1.891084	-16.100049	0.585990	-1.494520	0.007921
4	3.839458	6.651639	6.469198	3.908403	2.628005	2.257027	1.005447	0.580626	0.011008
5	-2.647614	-6.825646	-7.995123	-4.084731	-2.129535	-3.510195	-0.763196	-0.655849	-0.008920
6	-1.083630	6.278366	-14.212379	-6.128876	-2.087125	11.836548	-0.601072	1.160835	-0.008742
STO	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000
SUM	-0.560551	1.205484	-1.206406	-0.824178	-0.633065	-0.149584	-0.079199	0.020704	-0.002652

INFINITE CONJUGATES

EFL	100.0045
BFL	83.5412
FFL	-88.9858
FNO	3.4908
IMG DIS	82.7638
OAL	31.8530
PARAXIAL IMAGE	
HT	57.7376
ANG	30.0000
ENTRANCE PUPIL	
DIA	28.6483
THI	30.7264
EXIT PUPIL	
DIA	23.9321
THI	0.0000

ORIGINAL OPTIMIZED USING CODE V® LOCAL OPTIMIZER



ABERRATION COEFFICIENTS AND FIRST ORDER QUANTITIES FOR THE LENS OBTAINED FROM ORIGINAL USING CODE V® LOCAL OPTIMIZER

THO SO..I

New lens from CVMACRO:cvnewlens.seq

Position 1, Wavelength = 587.6 NM

	SA	TCO	TAS	SAS	PTB	DST	AX	LAT	PTZ
1	-0.608133	-0.812664	-3.698325	-3.456995	-3.336330	-1.539892	-0.542838	-0.241803	-0.006865
	0.000000	0.000000	0.000000	0.000000	0.000000	ASPHERIC CONTRIBUTIONS			
2	0.003172	0.051884	2.523470	2.334864	2.240560	12.731372	0.166788	0.909451	0.004610
3	0.164913	-2.285896	12.191342	5.150146	1.629548	-23.795822	0.571154	-2.638969	0.003353
4	1.314307	5.892809	12.015742	6.144425	3.208767	9.183023	1.138440	1.701432	0.006602
5	-0.819748	-5.080800	-13.044253	-6.046292	-2.547312	-12.491650	-0.829371	-1.713483	-0.005241
6	-0.199606	2.293413	-10.569996	-4.714309	-1.786465	18.055307	-0.530439	2.031526	-0.003676
STO	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000

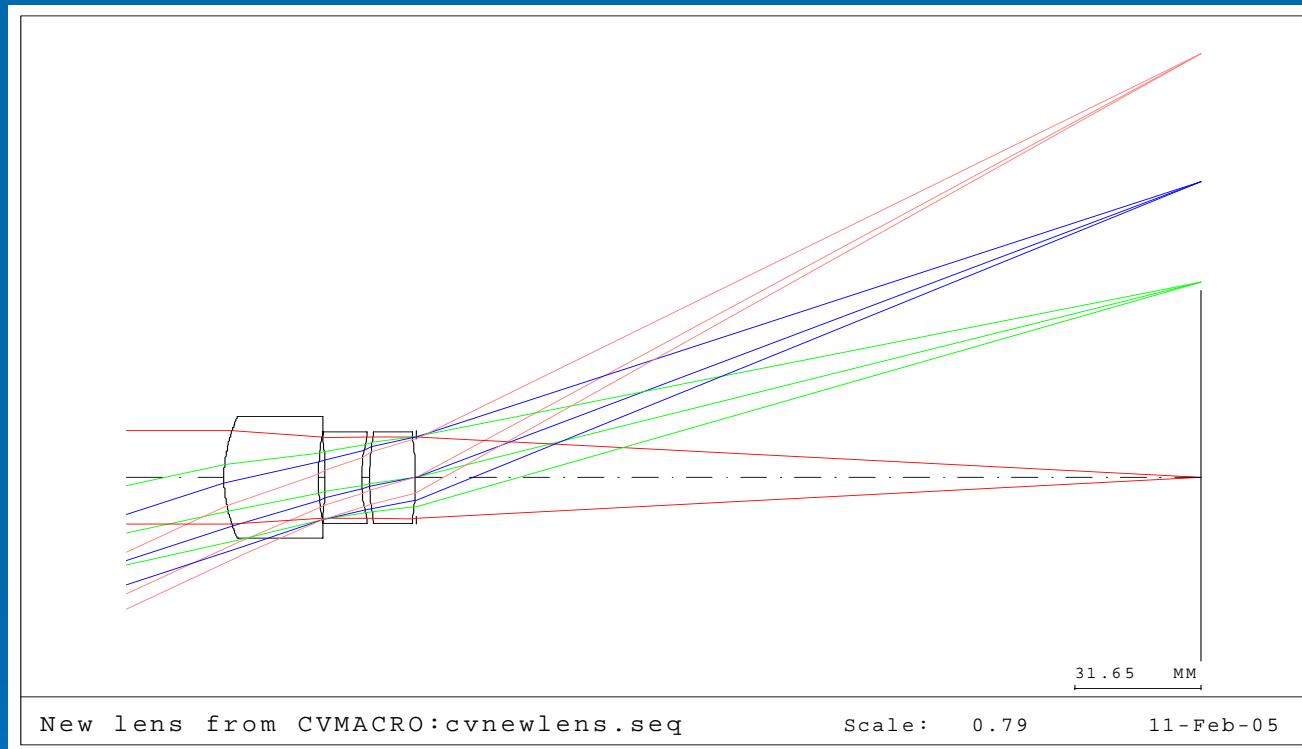
SUM -0.145095 0.058747 -0.582019 -0.588160 -0.591231

INFINITE CONJUGATES

EFL 201.8271
BFL 174.4329
FFL -196.6731
FNO 6.9844
IMG DIS 173.1540
OAL 43.8958
PARAXIAL IMAGE
HT 116.5249
ANG 30.0000
ENTRANCE PUPIL
DIA 28.8968
THI 36.8502
EXIT PUPIL
DIA 24.9746
THI 0.0000

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GECCO 2005, ECP Track

LENS OBTAINED FROM ORIGINAL USING CODE V® GLOBAL SYNTHESIS



ABERRATION COEFFICIENTS AND FIRST ORDER QUANTITIES FOR THE LENS OBTAINED FROM ORIGINAL USING CODE V® GLOBAL SYNTHESIS

THO SO..I

New lens from CVMACRO:cvnewlens.seq

Position 1, Wavelength = 587.6 NM

	SA	TCO	TAS	SAS	PTB	DST	AX	LAT	PTZ
1	-0.482042	-0.803029	-3.783457	-3.486177	-3.337537	-1.935865	-0.543035	-0.301546	-0.006111
	0.000000	0.000000	0.000000	0.000000	0.000000	ASPHERIC CONTRIBUTIONS			
2	0.004330	0.075158	2.708839	2.418970	2.274036	13.994217	0.176006	1.018229	0.004163
3	0.132593	-2.037016	12.091551	5.137188	1.660007	-26.307504	0.579293	-2.966554	0.003039
4	1.092444	5.659573	12.958098	6.442479	3.184669	11.125417	1.161571	2.005899	0.005831
5	-0.707649	-4.917058	-13.973973	-6.381554	-2.585344	-14.780617	-0.858430	-1.988250	-0.004733
6	-0.161585	2.058142	-10.527054	-4.701518	-1.788750	19.961351	-0.537644	2.282689	-0.003275
STO	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000

SUM -0.121909 0.035770 -0.525996 -0.570612 -0.592919 2

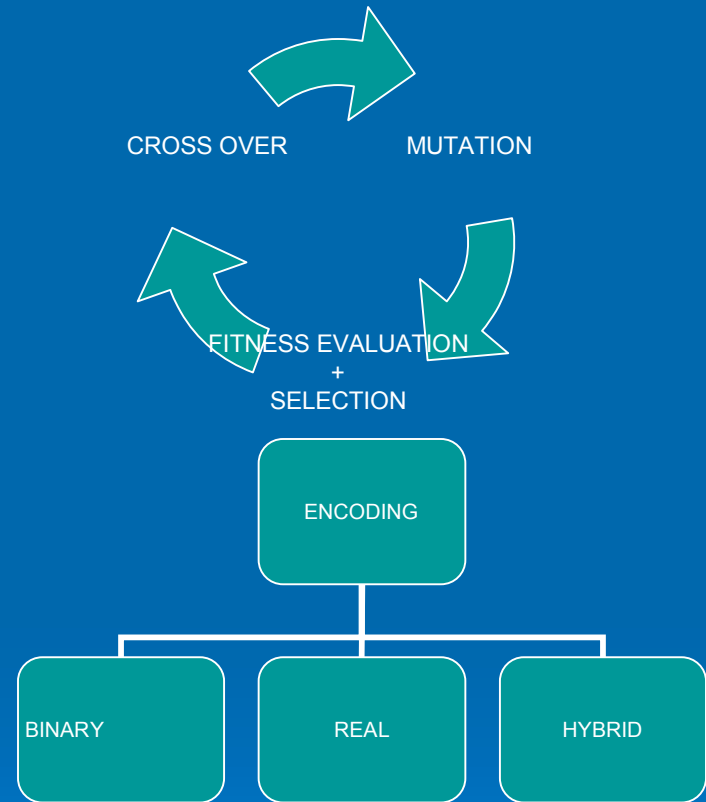
INFINITE CONJUGATES

EFL 226.8151
BFL 197.6181
FFL -220.3017
FNO 7.8491
IMG DIS 196.3041
OAL 47.9339
PARAXIAL IMAGE
HT 130.9517
ANG 30.0000
ENTRANCE PUPIL
DIA 28.8968
THI 40.0240
EXIT PUPIL
DIA 25.1770
THI 0.0000

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Missouri- St. Louis & Rolla,
GECCO 2005, ECP Track

WHY GA?

- To obtain Global Optima.



WHY MULTI-OBJECTIVE GA?

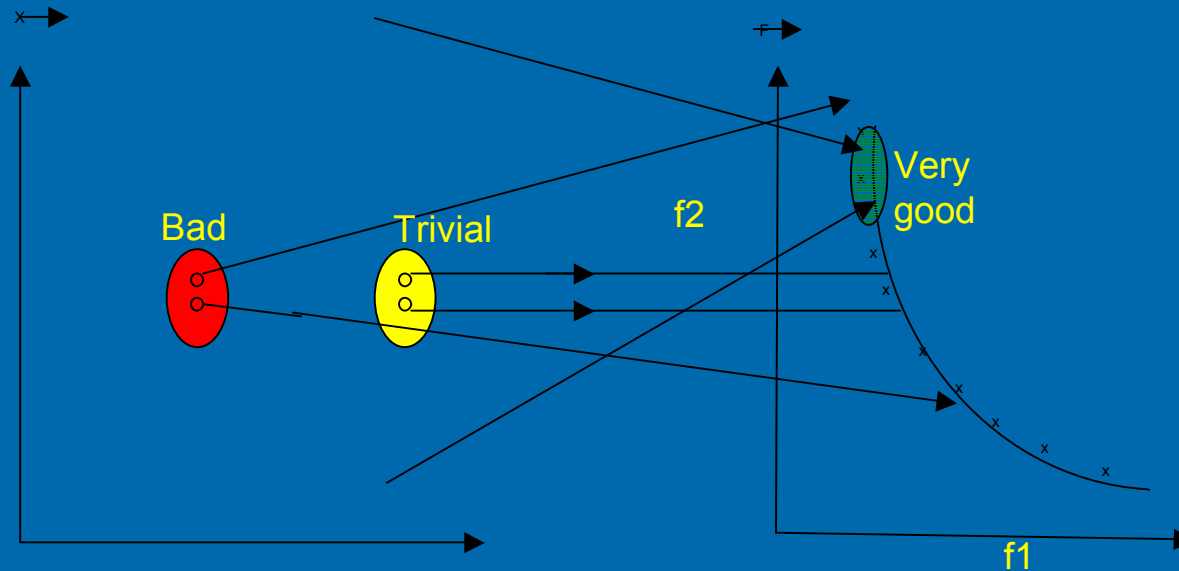


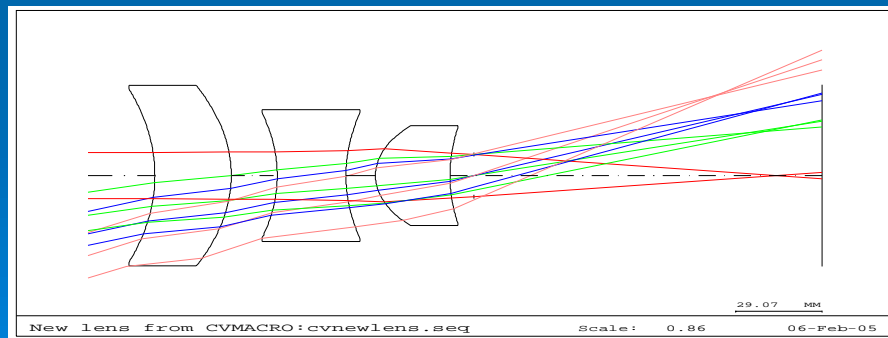
Figure 1. Mapping from Constructional Parameter Space X to the Objective Function Space F is shown. This figure shows three categories of solutions mapped from X to F on a particular Pareto-optimal front. When two nearby points in X maps to two far away points in F , we have an undesired situation. Slight perturbations of parameters during manufacturing can lead to severe performance degrading. When two nearby points in X maps to two nearby points in F , we have the trivial situation. **When two far away points in X maps to two nearby points in F , we obtain alternate choices for manufacturing the system.**

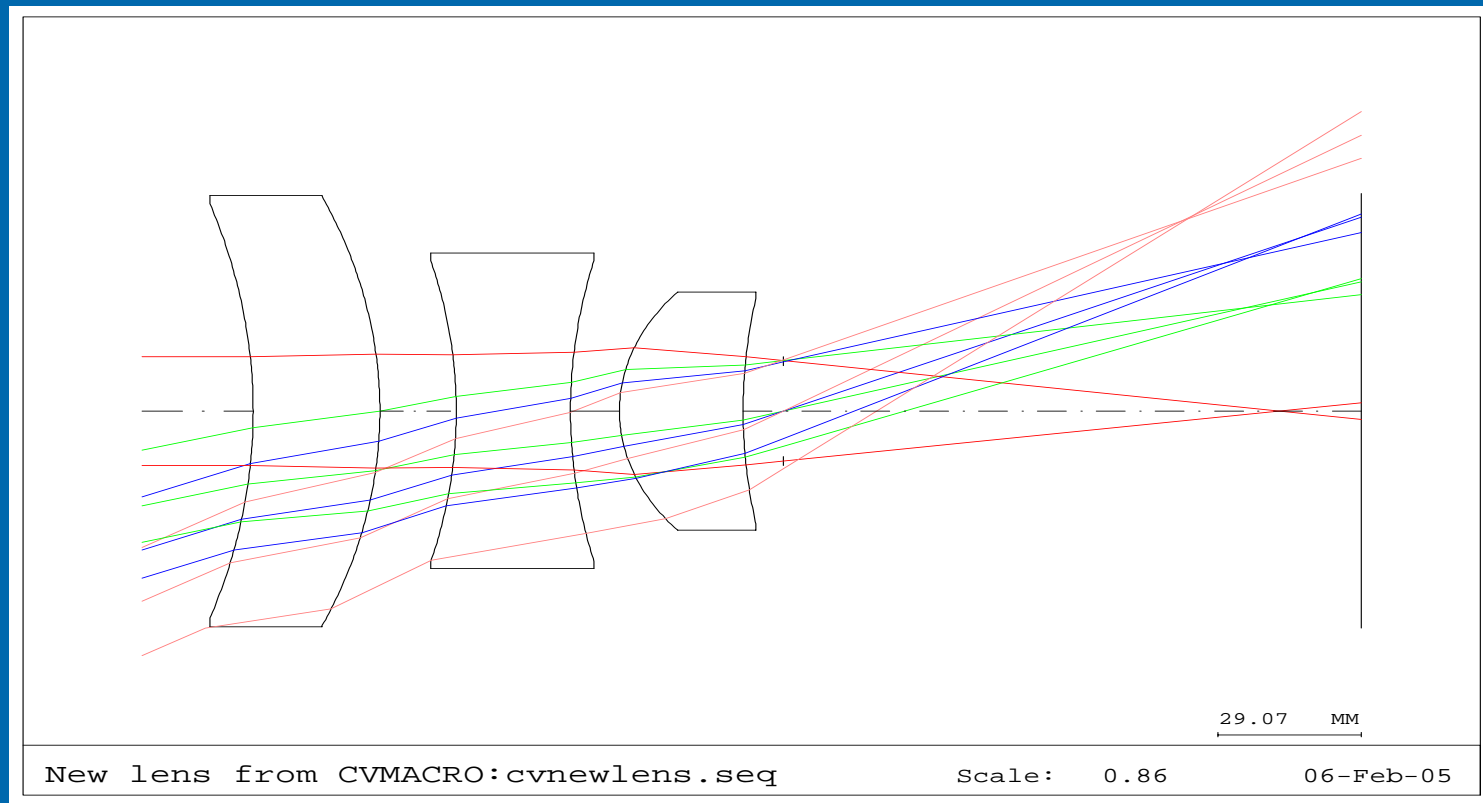
1. **Alternate manufacturing choices for a given performance requirement is possible (see above).**
2. Multiple Pareto-Optima can be obtained in a single run.
3. Dependence on Optical Engineering insight can be reduced on selecting suitable merit function and starting points.

WHAT IS HYBRID CODING?

1. Object is placed on the left side of the system.
2. Radius is Positive if Ray Travels from the Vertex of Lens to the Center of Curvature. Otherwise, Radius of curvature is Negative .
3. Define an integer representing the shape of the lens system.
Assign a Digit (-1) for Positive Curvature and Digit (+1) for Negative Curvature). See the figure below for illustration.
4. The value of a radius will come from two different variables. One is a Decimal Number representing the magnitude of radius. The other is the SIGN(+ or -) of the radius. The SIGNS for all the radii are encoded into a single Binary Integer.

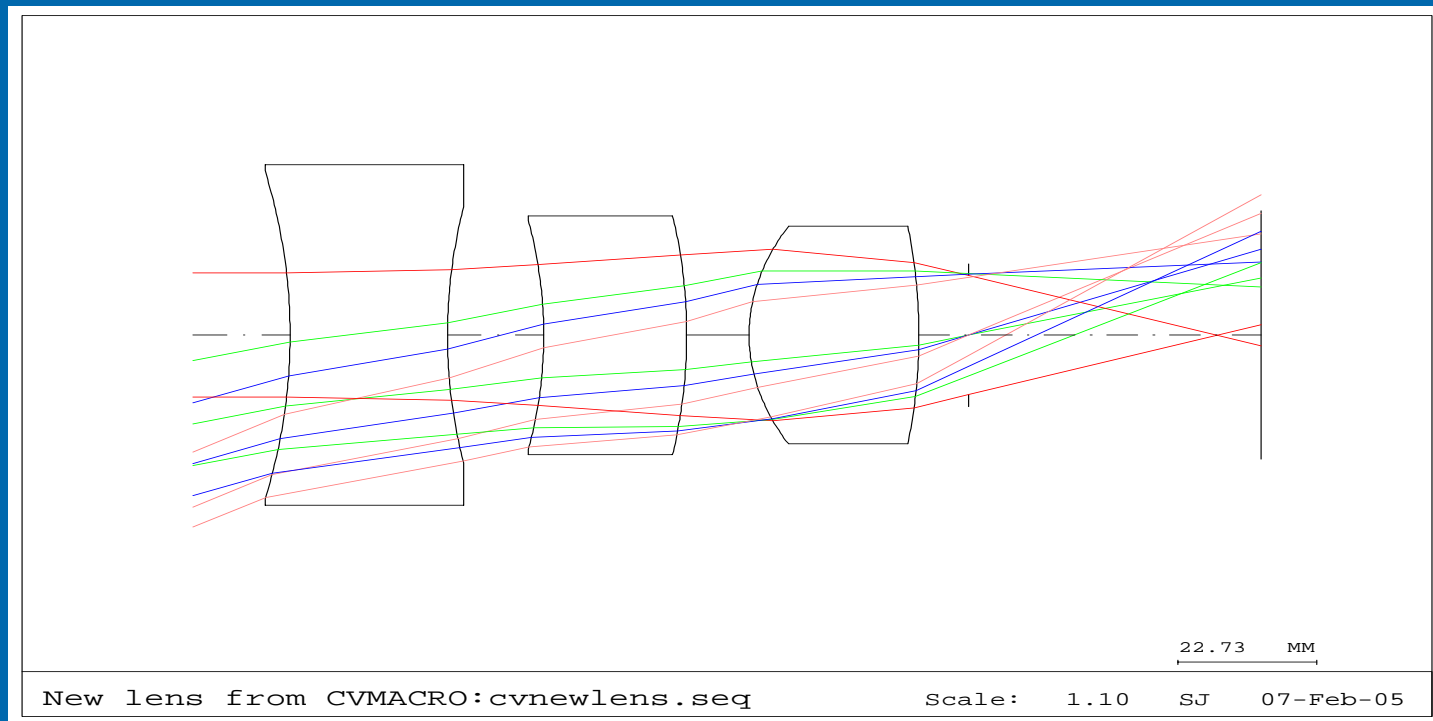
56 == 111000(binary) == (-,-,-,+,+,+)





This corresponds to the solution 2 in Table 1, belongs to region 56, has F/# 4.4, SA=-1.98 and DST= -0.44. The image is too curved.

56 ==111000(binary)==(-,-,-,+,+,+)



This corresponds to the solution 12 in Table 1, belongs to region 45, has $F/\#$ 1.73, $SA=-1.9$ and $DST=-0.49$. The image suffers from astigmatism and coma, but image is flat.

45 == 101101 (binary) == (-,+,-,-,+,-)

WHY HYBRID CODING?

REAL CODING OF THE RADIUS IS BAD because.....

- **Abrupt change from positive to negative *INFINITY* at a *FLAT SURFACE*.**
- Very small values of radii are not realizable. They correspond to infinite curvature.
- Difficult to get good solutions when ***any of the six radii of curvatures*** is less than 10 mm in absolute value.
- In the beginning, when candidates are randomly generated with radius between -200 mm and 200 mm, the probability that it lies between -10 mm and 10 mm is 0.05 ***for any one radius***. Probability that ***any one of the six radii lie between -10 mm and 10 mm is approximately 0.3***.
- ***So among the initial generation, 30% of the population members are bound to be bad candidates. Only the remaining 70% are the possible good candidates.***
- In any given generation after the evolution of a Pareto-front, the cross-over takes place between selected candidates. The probability that a ***selected pair has at least one radius with opposite signs*** is approximately

$$\{1-(0.5)(0.5)(0.5)(0.5)(0.5)(0.5)\} = 0.984.$$

WHY HYBRID CODING? (continued)

- *The probability for their magnitudes to differ by at least 20 mm is 0.79. The cross-over is likely to result in children with radii in the prohibited region between -10 mm and 10 mm if the magnitudes of the radii differ by less than 20 mm. This is given by $1 - 0.79 = 0.21$.*

$$(R1 - R2)/2 < 10 \text{ mm}$$

- *Hence the probability for a selected pair on Pareto-Optimal front generating undesired children after cross over is given by $\{ (0.984) \times (0.21) \}$. This essentially reduces the effectiveness of cross over by a factor of 20%.*
- During cross over, to reach from positive values of radius to negative values of radius, we have to cross positive infinity and negative infinity. Only a hyper cube around the origin of the system (where positive and negative infinities are placed side by side) is the allowed region for the radii.

GA and PROBLEM SPECIFICATIONS

- NSGA2
- Number of generations is 34, Population size is 130
- Cross over probability is 1, real coded mutation probability is 0.0769, Uniform Binary Cross over is employed, binary coded mutation probability is 0.166667 and the cross over parameter in SBX operator is 100.
- The NSGA2 code downloaded from **Deb's** web site was used with necessary modifications for hybrid coding.
- The radii of curvature is allowed to vary between - 200mm and 200mm. The thicknesses were varied from 0.01mm to 30mm.

RESULTS

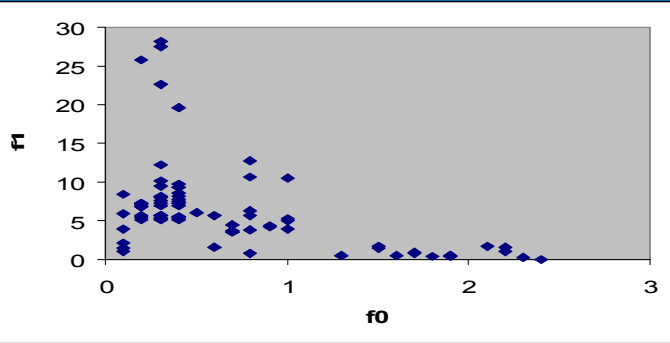


Figure2. A diverse set of good solutions belonging to different Pareto-Fronts is shown.

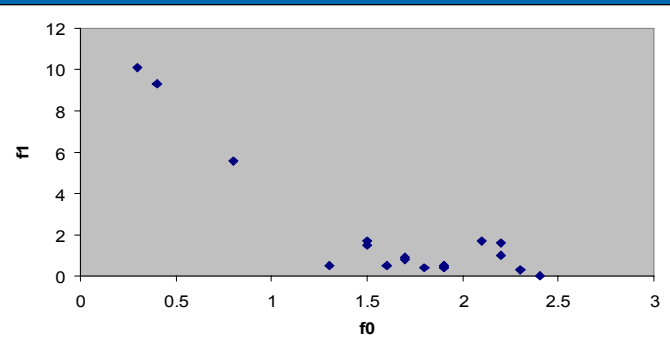


Figure4. A diverse set of good solutions belonging to different Pareto-Fronts is shown when only positive value for the stop to image distance is accepted.

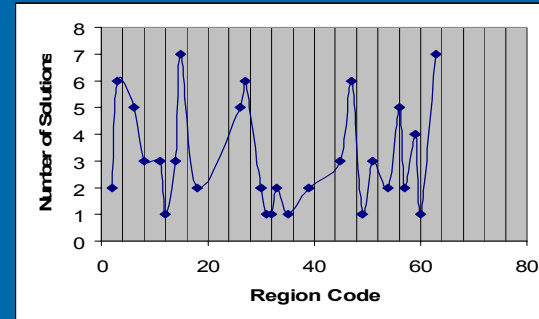


Figure3. Number of Solutions plotted against Region code. Show diversity explicitly.

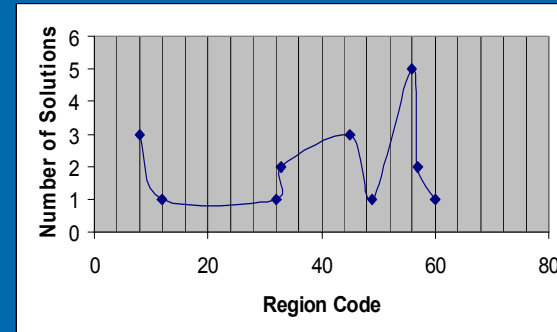


Figure5. Number of Solutions plotted against Region Code when only positive value for the stop to image distance is accepted. Show diversity explicitly.

PARETO- OPTIMA FROM NSGA2

Table1

NO	CODE	F/#	SA	DST
1	49	1.7	-0.84	1.9
2	56	4.4	-1.98	-0.44
3	60	2	-0.39	3.5
4	56	4.4	-2.3	-0.57
5	56	4.5	-1.97	-0.56
6	33	1.8	-1.72	0.94
7	56	4.5	-2.2	-1.7
8	8	5.4	-2.2	-1.1
9	33	1.69	-1.8	0.48
10	32	3.1	-1.57	-1.76
11	12	2.4	-0.43	9.4
12	45	1.73	-1.9	-0.49
13	57	2.1	-1.6	1.6
14	41	1.42	-2.5	-0.08
15	45	1.59	-2.3	-0.32
16	56	4.48	-1.97	-0.558
17	8	5.5	-1.6	-0.58
18	8	5.09	-1.4	0.55
19	57	2.09	-1.7	0.88

CODE V® AUTOMATIC DESIGN OPTIMIZATION

Table2

NO	CODE	F/#	SA	DST
1	49	3.4	-0.27	-2.8
2	57	17.8	-0.13	-1.36
3	61	12	-0.16	-3.1
4	57	16.5	-0.18	4
5	57	11.7	-0.23	-2.4
6	49	5.6	-0.22	-9.5
7	48	112.8	-0.1	2.4
8	9	19.1	-0.09	0.94
9	33	6.86	-0.42	-11.8
10	33	5.7	-0.47	-9.9
11	57	13.5	-0.23	-4.3
12	61	9.2	-0.28	-9
13	57	10.5	-0.27	-6.6
14	49	3.36	-0.38	-9.8
15	49	5.05	-0.24	-10.3
16	57	11.66	-0.23	-2.4
17	9	13.16	-0.09	0.28
18	9	15.9	-0.086	0.4
19	9	13	-0.08	0.62

CODE V® GLOBAL SYNTHESIS

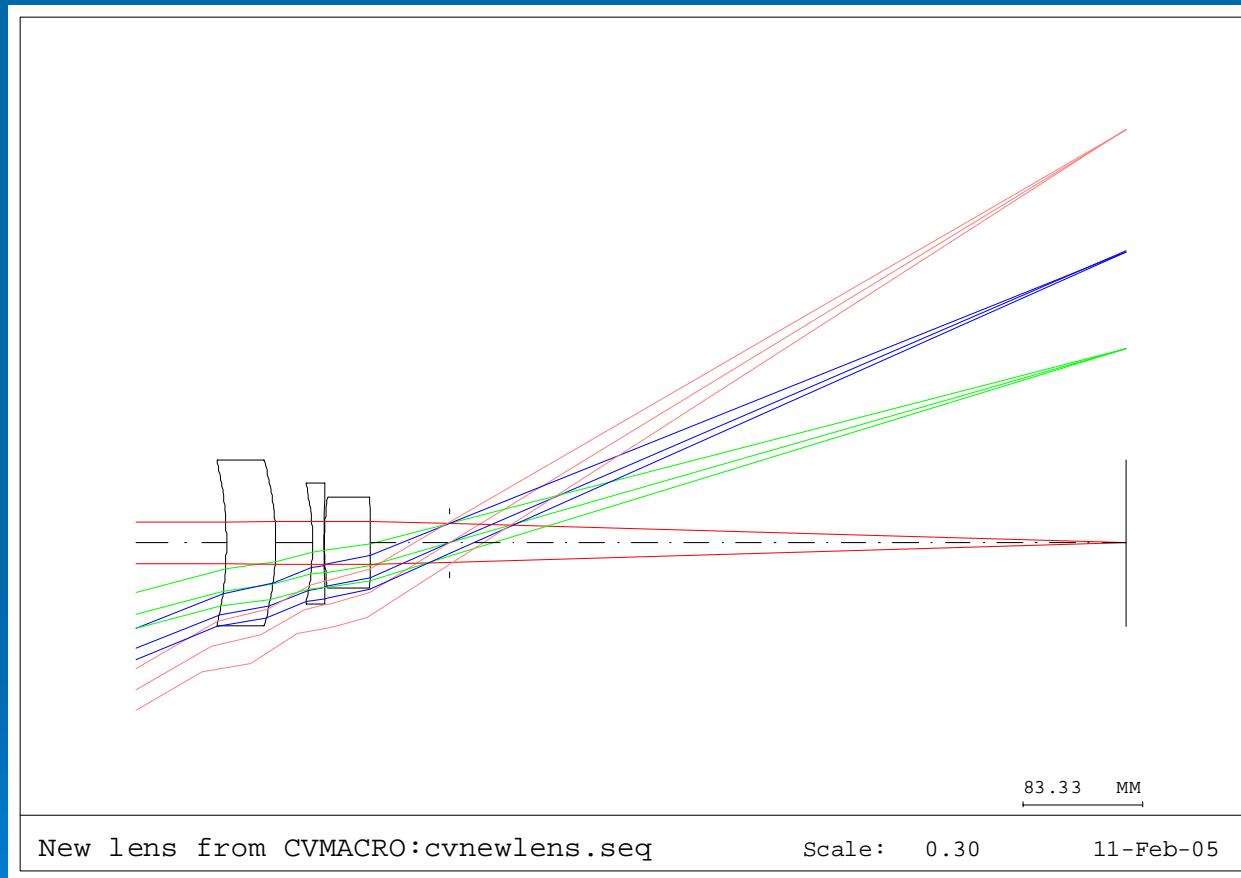
Table3

NO	CODE	F/#	SA	DST
1	49	4.2	-0.21	-2.9
2	57	26.6	-0.09	2.3
3	57	21.9	-0.11	-1.43
4	57	19.5	-0.15	3.4
5	57	15.4	-0.2	-1.4
6	49	13.5	0.29	-15.4
7	48	193.1	-0.08	-5.9
8	9	15.5	-0.08	0.29
9	0	48.4	-0.16	6.1
10	0	44.6	-0.18	8.5
11	57	20.4	-0.18	-3.2
12	57	18.9	-0.18	-2.7
13	57	17.6	-0.19	-2.5
14	49	4.6	-0.36	-14.9
15	49	5.6	-0.19	-11.7
16	57	15.4	-0.2	-1.38
17	9	12.7	-0.08	0.32
18	9	14.3	-0.08	0.07
19	9	12.8	-0.08	0.33

Table4

NO	CODE	F:NO	EFL	BFL	OAL	SA	DST	Auto- OPT Code	F:NO	EFL	BFL	OAL	SA	DST	GLOBAL - OPT CODE	F:NO	EFL	BFL	OAL	SA	DST
1	49	1.7	48.3	31.8	132.7	-0.84	1.9	49	3.4	97.6	95.4	75.4	-0.27	-2.8	49	4.2	121.1	122.4	75.4	-0.21	-2.9
2	56	4.4	128.2	117.2	107.4	-1.98	-0.44	57	17.8	515.6	478.4	155	-0.13	-1.36	57	26.6	768.2	711	194.5	-0.09	2.3
3	60	2	58.4	37.4	110.2	-0.39	3.5	61	12	346.3	334.2	114.3	-0.16	-3.1	57	21.9	634.1	585.9	178.1	-0.11	-1.43
4	56	4.4	128	117.9	116.4	-2.3	-0.57	57	16.5	476.1	399	158.5	-0.18	4	57	19.5	562.1	482.4	176.4	-0.15	3.4
5	56	4.5	128.3	117.6	108.6	-1.97	-0.56	57	11.7	334.3	304.8	128.7	-0.23	-2.4	57	15.4	441.1	406.6	133.8	-0.2	-1.4
6	33	1.8	51.3	44.9	108.3	-1.72	0.94	49	5.6	160.3	166.2	63.8	-0.22	-9.5	49	13.5	386.2	425.1	89.1	0.29	-15.4
7	56	4.5	129.5	120.2	117	-2.2	-1.7	48	112.8	3231.3	3148.7	144.7	-0.1	2.4	48	193.1	5533.4	5473.1	144.3	-0.08	-5.9
8	8	5.4	155.8	138.2	118.6	-2.2	-1.1	9	19.1	548.4	501.2	86.6	-0.09	0.94	9	15.5	443.1	402.3	80.6	-0.08	0.29
9	33	1.69	48.3	43	118.8	-1.8	0.48	33	6.86	196.4	206.1	153.6	-0.42	-11.8	0	48.4	1387.4	1306.5	188.6	-0.16	6.1
10	32	3.1	88	81.4	122.3	-1.57	-1.76	33	5.7	163.3	170.4	132.6	-0.47	-9.9	0	44.6	1278.3	1190	150.9	-0.18	8.5
11	12	2.4	119.2	67.9	44.9	-0.43	9.4	57	13.5	388.2	365.3	132.8	-0.23	-4.3	57	20.4	584.1	548.2	156.8	-0.18	-3.2
12	45	1.73	49.6	47.9	111.1	-1.9	-0.49	61	9.2	263.7	262.4	122.1	-0.28	-9	57	18.9	541.2	506	151.3	-0.18	-2.7
13	57	2.1	59.9	50.6	123.3	-1.6	1.6	57	10.5	301.7	289.7	127.4	-0.27	-6.6	57	17.6	505.3	470.9	148	-0.19	-2.5
14	41	1.42	40.5	38.1	116.6	-2.5	-0.08	49	3.36	96.1	105	132.2	-0.38	-9.8	49	4.6	132.1	151.4	177.7	-0.36	-14.9
15	45	1.59	45.5	44	107.9	-2.3	-0.32	49	5.05	144.7	149.7	72.5	-0.24	-10.3	49	5.6	160.3	166.1	82.8	-0.19	-11.7
16	56	4.48	128.3	117.6	108.6	-1.97	-0.558	57	11.66	334.3	304.8	128.7	-0.23	-2.4	57	15.4	440.8	406.4	133.8	-0.2	-1.38
17	8	5.5	157.9	131.4	108.2	-1.6	-0.58	9	13.16	377.1	340.5	73.2	-0.09	0.28	9	12.7	364.9	329	72.1	-0.08	0.32
18	8	5.09	145.9	118.2	120.1	-1.4	0.55	9	15.9	455.8	414.3	81	-0.086	0.4	9	14.3	409.5	370.8	78.4	-0.08	0.07
19	57	2.09	59.8	53.0	114.8	-1.7	0.88														

LENS OBTAINED FROM THE SOLUTION WITH **CODE=56** USING CODE V® LOCAL OPTIMIZER



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ABERRATION COEFFICIENTS AND FIRST ORDER QUANTITIES FOR THE LENS OBTAINED FROM SOLUTION WITH **CODE=56** USING CODE V® LOCAL OPTIMIZER

THO SOL

New lens from CVMACRO:cvnewlens.seq

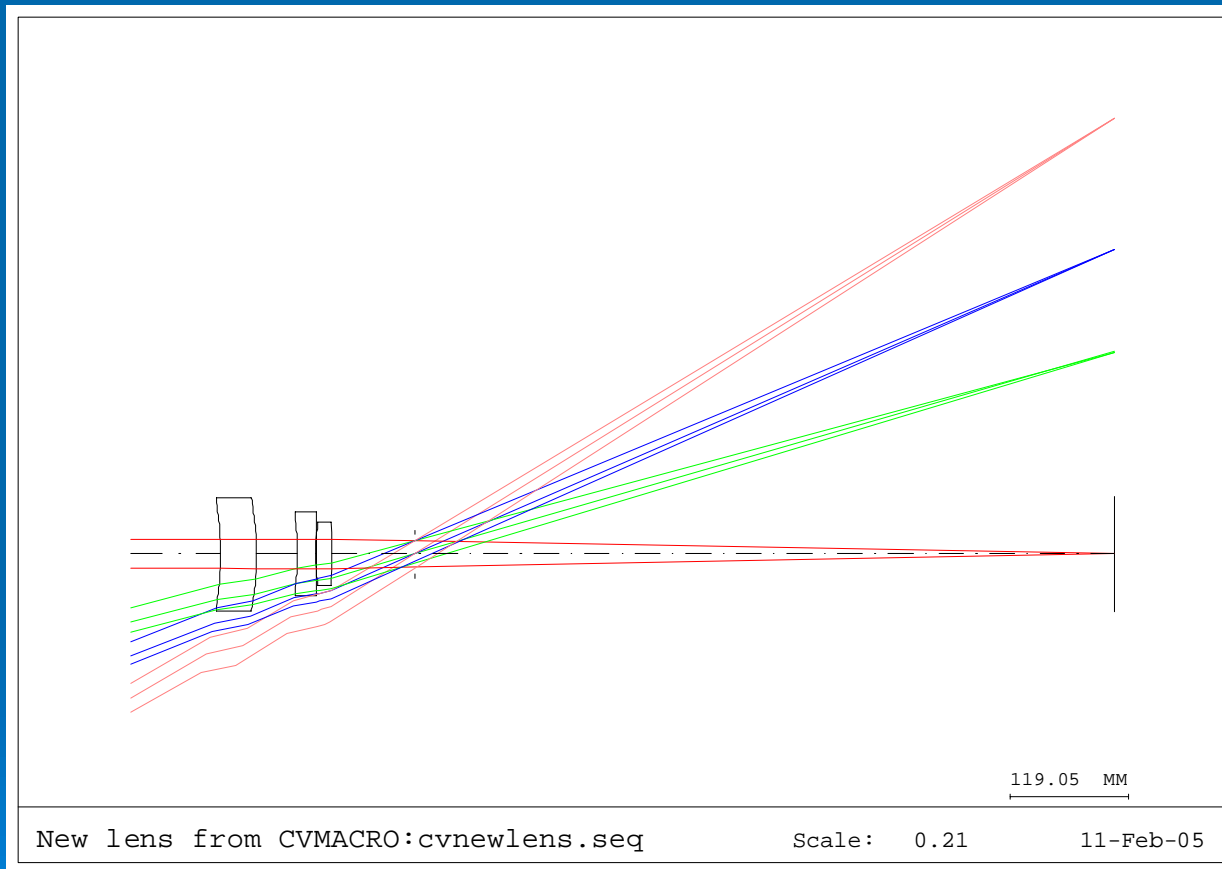
Position 1, Wavelength = 587.6 NM

	SA	TCO	TAS	SAS	PTB	DST	AX	LAT	PTZ	
1	0.011020	-0.494049	9.020681	4.098682	1.637682	-61.250164	0.266459	-3.981934	0.001319	
2	-0.030713	1.036604	-13.580869	-5.806042	-1.918629	65.320483	-0.371455	4.179028	-0.001545	
3	0.040196	-1.187688	14.055969	6.257586	2.358395	-61.631177	0.855603	-8.426860	0.001899	
4	0.020791	0.474080	3.864408	1.462198	0.261092	11.113664	0.543491	4.130891	0.000210	
5	-0.153993	-0.941530	-4.365198	-3.085948	-2.446323	-6.289285	-1.038630	-2.116769	-0.001970	
6	-0.018688	0.672163	-9.843243	-3.827030	-0.818923	51.380905	-0.465767	6.253293	-0.000660	
STO	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	
SUM	-0.129386	-0.440420	-0.848252	-0.900554	-0.926706	-1.355575	-0.210299	0.037650	-0.000746	

INFINITE CONJUGATES

EFL 515.6163
BFL 478.3903
FFL -431.5708
FNO 17.8434
IMG DIS 468.2569
OAL 154.9685
PARAXIAL IMAGE
HT 297.6912
ANG 30.0000
ENTRANCE PUPIL
DIA 28.8968
THI 124.1682
EXIT PUPIL
DIA 26.8105
THI 0.0000

LENS OBTAINED FROM THE SOLUTION WITH **CODE=56** USING CODE V® GLOBAL SYNTHESIS



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ABERRATION COEFFICIENTS AND FIRST ORDER QUANTITIES FOR THE LENS OBTAINED FROM SOLUTION WITH CODE=56 USING CODE V® GLOBAL SYNTHESIS

THO SO..I

New lens from CVMACRO:cvnewlens.seq

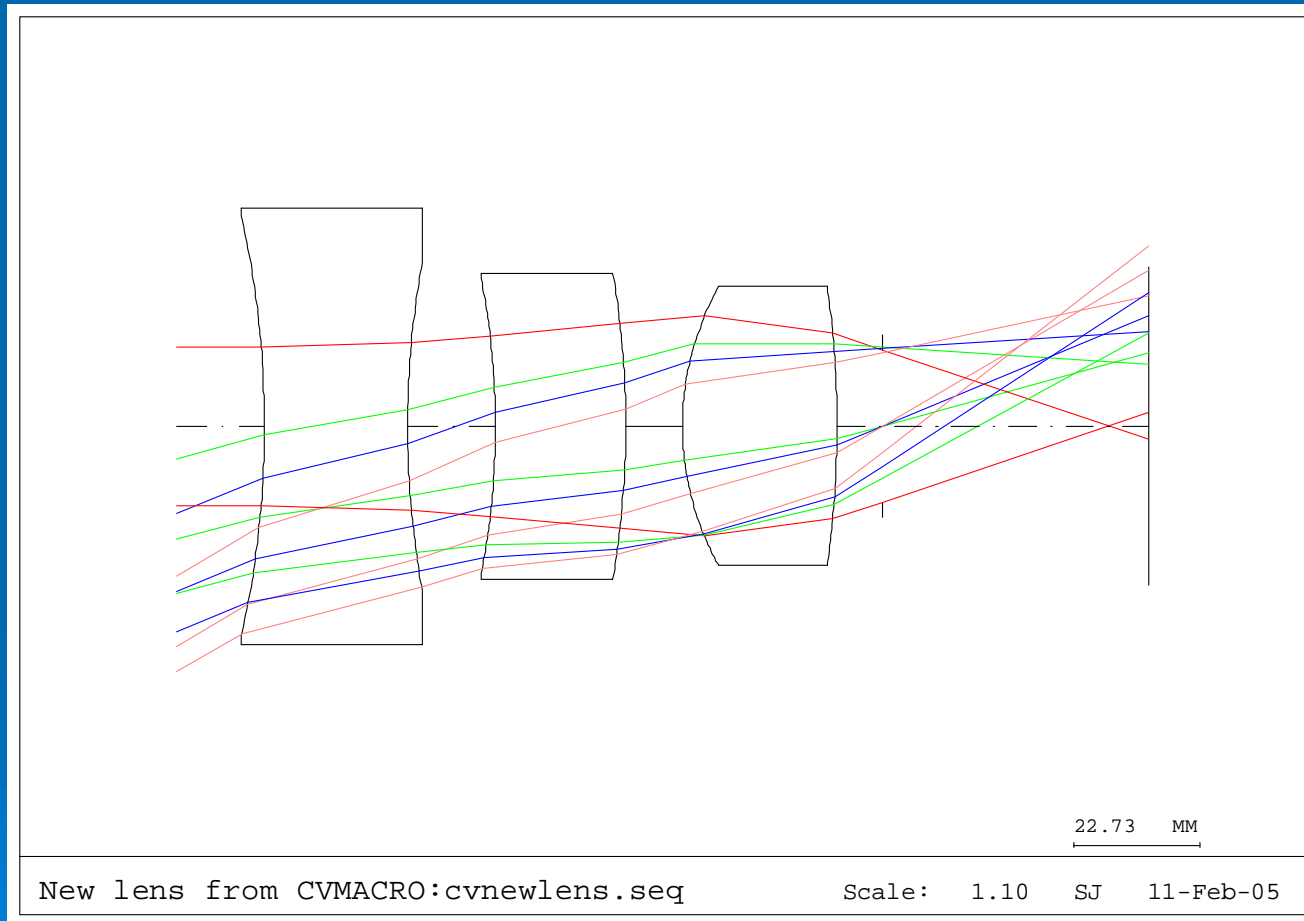
Position 1, Wavelength = 587.6 NM

	SA	TCO	TAS	SAS	PTB	DST	AX	LAT	PTZ	
1	0.005115	-0.329313	8.720887	4.009736	1.654160	-86.044872	0.269140	-5.775482	0.000894	
2	-0.013670	0.680281	-13.233450	-5.710426	-1.948913	94.724885	-0.367343	6.093513	-0.001053	
3	0.016567	-0.726833	12.958735	5.872490	2.329368	-85.880637	0.823572	-12.044106	0.001259	
4	0.017526	0.456900	4.518974	1.871994	0.548505	16.267649	0.684117	5.944984	0.000296	
5	-0.109020	-0.838960	-5.158552	-3.723841	-3.006486	-9.552245	-1.212876	-3.111220	-0.001625	
6	-0.004556	0.325221	-8.218361	-3.059112	-0.479487	72.793838	-0.380161	9.046214	-0.000259	
STO	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	
SUM	-0.088038	-0.432704	-0.411767	-0.739159	-0.902854	2.308618	-0.183551	0.153904	-0.000488	

INFINITE CONJUGATES

EFL 768.2492
BFL 710.9513
FFL -661.6422
FNO 26.5859
IMG DIS 699.9293
OAL 194.4777
PARAXIAL IMAGE
HT 443.5489
ANG 30.0000
ENTRANCE PUPIL
DIA 28.8968
THI 168.5228
EXIT PUPIL
DIA 26.7416
THI 0.0000

LENS SOLUTION WITH CODE=45



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ABERRATION COEFFICIENTS AND FIRST ORDER QUANTITIES FOR THE LENS SOLUTION WITH CODE=45

THO SOL

New lens from CVMACRO:cvnewlens.seq
Position 1, Wavelength = 587.6 NM

	SA	TCO	TAS	SAS	PTB	DST	AX	LAT	PTZ		
1	0.002907	-0.084319	1.035759	0.492239	0.220480	-4.759444	0.035873	-0.346856	0.001862		
2	0.051995	0.201762	0.494792	0.320809	0.233817	0.414958	0.080785	0.104494	0.001975		
3	-0.000701	0.035522	-0.288645	0.111384	0.311399	-1.881510	0.035484	-0.599396	0.002630		
4	0.000537	-0.029847	0.289631	-0.078804	-0.263021	1.459147	-0.031393	0.581274	-0.002222		
5	-1.091006	-0.710182	-1.168603	-1.065873	-1.014507	-0.231274	-0.540697	-0.117321	-0.008569		
6	-0.907005	4.468263	-7.639238	-2.747586	-0.301760	4.511899	-0.371475	0.610011	-0.002549		
STO	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000		

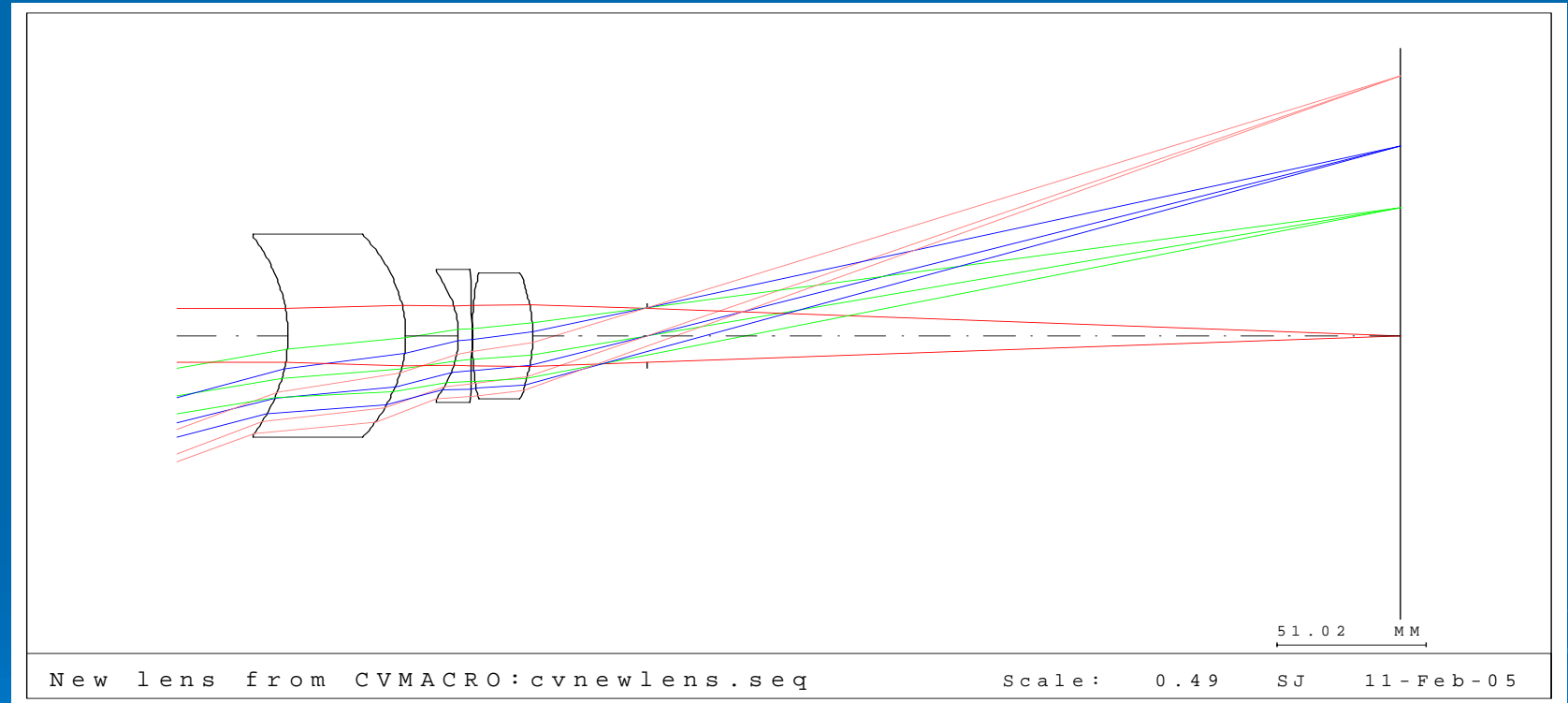
SUM -1.943272 3.881199 -7.276305 -2.967830 -0.813593 -0.486224 -0.791422 0.232205 -0.006872

INFINITE CONJUGATES

EFL 49.5924
BFL 47.8571
FFL 11.5667
FNO 1.7311
IMG DIS 47.8579
OAL 111.0817
PARAXIAL IMAGE
HT 28.6322
ANG 30.0000
ENTRANCE PUPIL
DIA 28.6483
THI 62.9573
EXIT PUPIL
DIA 27.6458
THI 0.0000

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LENS OBTAINED FROM THE SOLUTION WITH **CODE=45** USING CODE V® LOCAL OPTIMIZER



ABERRATION COEFFICIENTS AND FIRST ORDER QUANTITIES FOR THE LENS OBTAINED FROM SOLUTION WITH **CODE=45** USING CODE V® LOCAL OPTIMIZER

THO SO..I

New lens from CVMACRO:cvnewlens.seq

Position 1, Wavelength = 587.6 NM

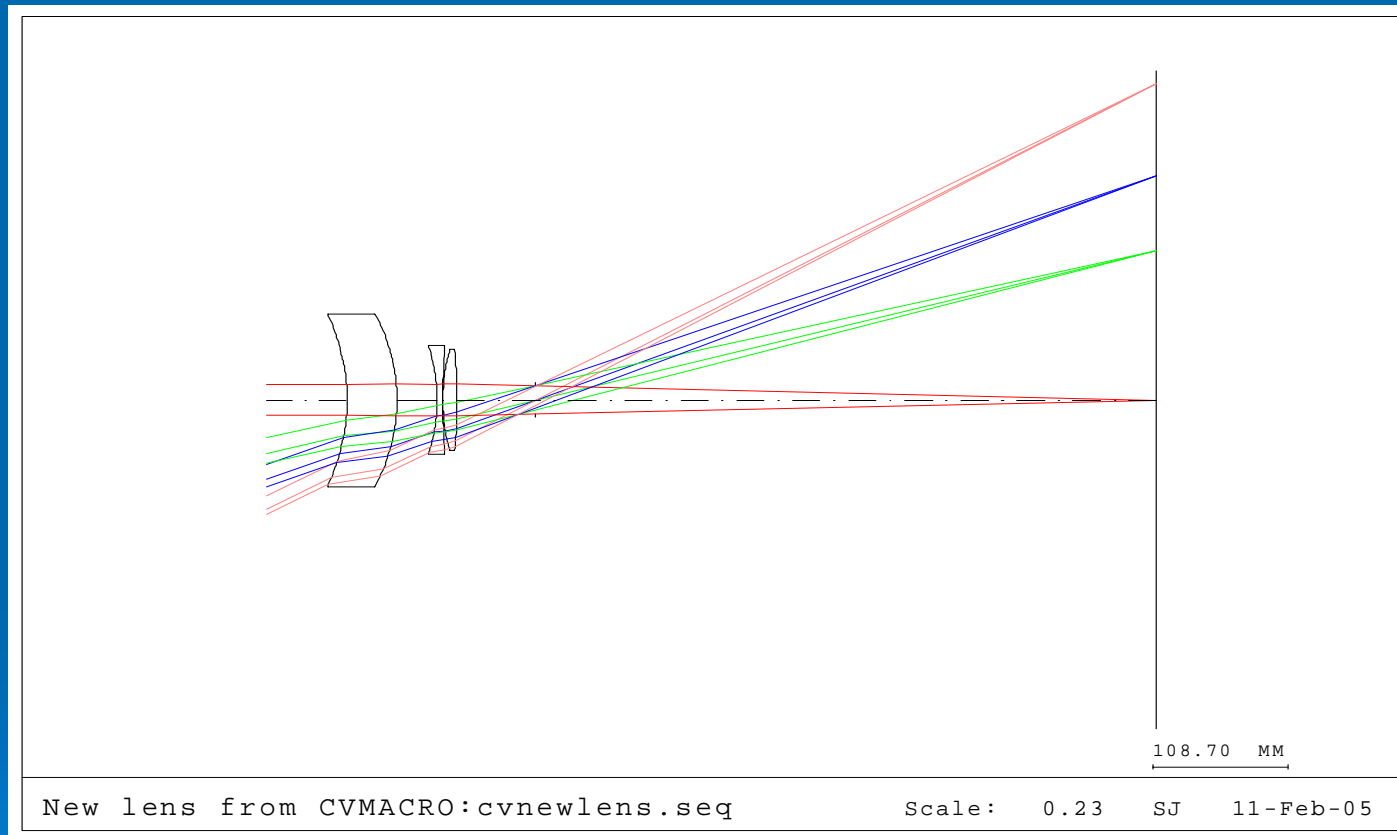
	SA	TCO	TAS	SAS	PTB	DST	AX	LAT	PTZ	
1	0.046715	-1.170472	11.470749	4.953729	1.695219	-41.372463	0.275821	-2.303596	0.002692	
2	-0.168264	2.820397	-17.715863	-7.210387	-1.957649	40.286110	-0.432731	2.417768	-0.003109	
3	0.372249	-4.813055	23.711844	9.882693	2.968118	-42.593296	1.189944	-5.128527	0.004714	
4	0.044355	0.671678	3.172780	0.912465	-0.217693	4.605904	0.431801	2.179631	-0.000346	
5	-0.261138	-1.332722	-3.321427	-1.809967	-1.054238	-3.079066	-0.769208	-1.308555	-0.001674	
6	-0.315862	4.030654	-19.231438	-7.801568	-2.086633	33.184779	-0.923343	3.927535	-0.003314	
STO	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	
SUM	-0.281945	0.206480	-1.913355	-1.073036	-0.652876	-8.968032	-0.227715	-0.215744	-0.0010	

INFINITE CONJUGATES

EFL 263.7445
BFL 262.4178
FFL -180.2502
FNO 9.2063
IMG DIS 256.1725
OAL 122.0984
PARAXIAL IMAGE
HT 152.2729
ANG 30.0000
ENTRANCE PUPIL
DIA 28.6483
THI 84.8277
EXIT PUPIL
DIA 28.5042
THI 0.0000

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LENS OBTAINED FROM THE SOLUTION WITH **CODE=45** USING CODE V® GLOBAL SYNTHESIS



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Missouri- St. Louis & Rolla,
GECCO 2005, ECP Track

ABERRATION COEFFICIENTS AND FIRST ORDER QUANTITIES FOR THE LENS OBTAINED FROM SOLUTION WITH **CODE=45** USING CODE V® GLOBAL SYNTHESIS

THO SO..I

New lens from CVMACRO:cvnewlens.seq

Position 1, Wavelength = 587.6 NM

	SA	TCO	TAS	SAS	PTB	DST	AX	LAT	PTZ	
1	0.015743	-0.667133	11.328422	5.046124	1.904974	-71.277931	0.309949	-4.378120	0.001474	
2	-0.035690	1.167691	-14.834057	-6.344370	-2.099527	69.190034	-0.410041	4.471795	-0.001625	
3	0.039247	-1.142247	13.499954	6.112357	2.418559	-59.298426	0.889313	-8.627580	0.001872	
4	0.053895	0.762781	4.261929	1.862901	0.663387	8.788535	0.798254	3.765890	0.000513	
5	-0.240511	-1.120226	-4.542613	-3.383133	-2.803393	-5.252522	-1.243367	-1.930404	-0.002170	
6	-0.017003	0.694838	-10.356335	-4.046456	-0.891517	55.119311	-0.493421	6.721198	-0.000690	
STO	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	
SUM	-0.184320	-0.304297	-0.642699	-0.752577	-0.807516	-2.731000	-0.149313	0.022778	-0.000625	

INFINITE CONJUGATES

EFL 541.2048
BFL 505.9707
FFL -451.9176
FNO 18.8913
IMG DIS 497.0927
OAL 151.3065
PARAXIAL IMAGE
HT 312.4647
ANG 30.0000
ENTRANCE PUPIL
DIA 28.6483
THI 126.9749
EXIT PUPIL
DIA 26.7832
THI 0.0000

CONCLUSIONS

- I have successfully demonstrated the usefulness of NSGA2 for Optical System optimization.
- We can obtain alternate manufacturing choices for a given set of objective functions. This was demonstrated with Siedel aberration coefficients corresponding to spherical aberration and distortion chosen as objectives.
- Hybrid encoding is introduced for the radii of curvatures and they were found to be better suited for the present problem.
- Diversity is clearly evident in the solutions, which is a significant improvement over earlier studies by Ono.
- The diverse Pareto-Optimal front was used as a starting point for single objective local and global optimization methods. They resulted in a range of excellent and diverse solutions. Some of their features are shown in Tables 1-4.

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- U.K. Chakraborty & C.Z. Janikow, An analysis of Gray versus binary encoding in genetic search, *Information Sciences*, 156(3-4), 2003, pp. 253-269.
- <http://www.iitk.ac.in/kangal/soft.htm>
This is the web site of K. Deb where NSGA2 was obtained.
- <http://delta.cs.cinvestav.mx/~ccoello/EMOO/>
This site is maintained by [Dr. Carlos A. Coello Coello](#). It is a repository of resources on Multi-objective optimization.

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- * I would like to thank Optical Research Associates for providing me a student license and full support for CODE V®.
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