A New Synthesis of Symmetric Functions

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Abstract

A new approach to synthesizing totally symmetric Boolean functions is presented. First, a novel cellular array is introduced for synthesizing unate symmetric functions. Using this module, a general symmetric function is then realized following a unate decomposition method. The cellular structure is simple and universal – it uses only 2-input, 2-output AND-OR cells, and admits a recursive construction. The design provides a significant reduction in hardware cost compared to other existing techniques.

1. Introduction

Synthesis of symmetric Boolean functions is a classical problem in switching theory, and several techniques are well known [1-4, 9]. Since symmetric functions play a key role in cryptology [5], design of easily testable circuits to realize them has received considerable attention recently. This paper presents a new approach to synthesizing totally symmetric functions. We first introduce a novel cellular logic array for realizing unate symmetric functions. These modules are constructed using a simple iterative arrangement of 2-input, 2-output AND-OR cells. A similar network known as digital summation threshold logic (DSTL) array was reported earlier by Hurst [7] in connection to threshold logic. Testable logic design using DSTL arrays for detecting stuck-at and bridging faults appeared in [6]. In this work, we present a new and compact cellular structure that realizes the same set of logic functions as that of a DSTL array with significant reduction in hardware cost and delay. Following a unate decomposition technique, we show that any totally symmetric function can be synthesized using these modules. Our design approach is universally applicable to any general symmetric function and hardware cost reduces drastically compared to other existing designs [2, 3].

2. Preliminaries

A Boolean function is called *unate*, if each variable appears either in complemented or uncomplemented form (but not both) in its minimum sum-of-products (s-o-p) expression. A function *is positive (negative) unate* if each variable appears in complemented (uncomplemented) form in its minimum so-p. A *vertex (minterm)* is a set of variables in which every

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variable appears once. The *weight* w of a vertex v is the number of uncomplemented variables appearing in v.

A switching function $f(x_1, x_2, ..., x_n)$ is called *totally* symmetric with respect to the variables $(x_1, x_2, ..., x_n)$, if it is invariant under any permutation of the variables [4]. Total symmetry can be specified by a set of integers (called anumbers) A = $(a_1, ..., a_k)$, where A $\subseteq \{0, 1, 2, ..., n\}$; all the vertices with weight $w \in A$ will appear as true minterms in the function. Henceforth, by a symmetric function, we would mean a function with total symmetry. An n-variable symmetric function is denoted as Sⁿ(a_i,..., a_j, ..., a_k). A symmetric function is called consecutive, if the set A consists of only consecutive integers $(a_l, a_{l+1}, ..., a_r)$. Such a consecutive symmetric function is expressed by $S^{n}(a_{l} - a_{r})$ where l < r. For n variables, we can construct $2^{n+1}-2$ different symmetric functions (excluding constant functions 0 and 1). A totally symmetric function $S^{n}(A)$ can be expressed uniquely as a union of maximal consecutive symmetric functions, such that $S^{n}(A) = S^{n}(A_{1}) + S^{n}(A_{2})$ +....+ $S^n(A_m)$, such that m is minimum and $\forall i, j$, $1 \le i, j \le m, A_i \cap A_j = \emptyset$, whenever $i \ne j$.

Example 1: The symmetric function $S^{12}(1,2,5,6,7,9,10)$ can be expressed as $S^{12}(1-2)+S^{12}(5-7)+S^{12}(9-10)$, where $S^{12}(1-2)$, $S^{12}(5-7)$ and $S^{12}(9-10)$ are maximal consecutive symmetric functions.

A function is called *unate symmetric* if it is both unate and symmetric. It can be shown that a unate symmetric function is always consecutive and can be expressed as $S^n(a_l, a_r)$, where either $a_l = 0$ or $a_r = n$. If it is positive unate, then it must be either $S^n(n)$ or any of the following (n-1) functions: $S^n(1-n)$, $S^n(2-n)$, $S^n(3-n)$,..., $S^n((n-1) - n)$. We express $S^n(n)$ as $u_n(n)$, and $S^n(a_l, a_r)$ as $u_l(n)$ for $1 \le l \le (n-1)$.

Theorem 1[3]: A consecutive symmetric function $S^n(a_l a_r)$, $a_l \neq a_r$, l < r, can be expressed as a composition of two unate and consecutive symmetric functions as follows:

(i) $S^{n}(a_{1}-a_{r}) = S^{n}(a_{1}-a_{n}) \overline{S}^{n}(a_{r+1}-a_{n})$ (ii) $S^{n}(a_{1}-a_{r}) = \overline{S}^{n}(0-a_{l-1}) \overline{S}^{n}(a_{r+1}-a_{n})$ (iii) $S^{n}(a_{1}-a_{r}) = S^{n}(0-a_{r}) \overline{S}^{n}(0-a_{l-1})$ (iv) $S^{n}(a_{1}-a_{r}) = S^{n}(0-a_{r}) S^{n}(a_{1}-a_{n}).$

3. DSTL array

The DSTL array proposed by Hurst [7] is an n-input and noutput cellular array, consisting of an iterative arrangement of identical cells having a uniform interconnection pattern among them. The design is shown in the Fig. 1a, where each cell consists of a two-input AND gate and an OR gate as shown in Fig. 1b. There are n-inputs lines $x_1, x_2, x_3,..., x_n$, and n output lines $u_1(n), u_2(n), u_3(n),..., u_n(n)$ in the array. Each output u_i , implements a unate symmetric function as described below:



4. Proposed technique

4.1 Synthesis for unate symmetric functions

We first introduce a basic logic module, which is similar to DSTL array in functionality, but more compact in structure.

4.1.1 Basic module

Our basic component Module(n) is a logic block with n input lines and n output lines (Fig. 2a). It consists of an iterative arrangement of cells, where each cell consists of a two-input AND gate and a two-input OR gate as in a DSTL array [7]. For ease of representation, we redraw the cell as shown in Fig. 2b. Though we use the same cells as in [7], our design differs significantly from the DSTL structure as far as the interconnections of cells are concerned.

Example 2: For n = 4, the DSTL array and the proposed logic module are shown in Figs. 3a and 3b. The new design needs fewer cells and has less delay compared to the DSTL array.



 $u_n \ u_{n-1} \ u_2 \ u_1$

Fig. 1a: Basic DSTL array

Fig. 1b: A DSTL cell





Fig. 2a: Module(n)

Fig. 2b: AND-OR cell





Fig. 3a: 4-variable DSTL array

Fig 3b: 4-variable proposed array



Fig. 4: Interconnect(n)



Fig. 5: Cell-cluster(M)

4.1.2 Basic structures

We use the following basic structures for our design.

Interconnect(n): Let n = even. The module Interconnect(n) provides a one-to-one and onto connection from n inputs a_1 , a_2 , a_3 ,..., a_n to n outputs b_1 , b_2 , b_3 ,..., b_n . The mapping, which is analogous to shuffle-exchange, can be expressed as

(i) for
$$i \le n/2$$
, $b_i = a_{2i-1}$
and (ii) for $i > n/2$, $b_i = a_{i-n/2}$

An example is shown in Fig. 4.

Cell-Cluster(M): This consists of M cells in parallel (see Fig. 5), where each cell is shown in Fig. 2b. The value of M may be even or odd.

Connection[n: 1-to-2] : This uses Interconnect(n-4), and is shown in Fig. 6.

Connection[n: 2-to-3]: This depends on the number of variables. The outputs of stage-2 are divided into two parts, each having (n/2) inputs. The corresponding outputs of each partition are paired together.



Fig. 6: Connection[n: 1-to-2]

4.1.3 Complete module (for n = even)

The details of Module(n) are shown in Fig. 7. It consists of three stages, each having n inputs and n outputs.

First-stage: This is first defined for n = even. It consists of $\lceil \log n \rceil$ levels as shown in Fig. 8. Each level consists of several cells in parallel.

Example 3: The first-stage for n = 8 and 6 are shown in Figs. 9a and 9b respectively.

For n = odd, we first design the first-stage for (n+1) inputs. Then, we set one input variable to logic 0 and remove the affected logic cells from the circuit level by level.

Example 4: The first-stage for n = 7 is shown in Fig. 10a. An equivalent realization is shown in Fig. 10b.

Hardware requirement: For n = even, the number of cells in the first-stage circuit is $n/2 \lceil \log n \rceil$.

Second-stage: The second stage consists of two parts, each implemented with a Module((n-2)/2). It is shown Fig. 11. Outputs of this stage are connected to the third-stage.

Third-stage: The third stage consists of a cascade of cells whose strucure is shown in Fig. 12.

Example 5: The overall designs for Module(6) and Module(8) are shown in Figs. 13a and 13b.

Example 6: Module(16) is shown in Fig. 14.



Fig. 7: Structure of Module(n)



Fig. 8: First-stage of Module(n)



Fig. 9a: First-stage for n = 8

Fig. 9b: First-stage for n = 6



Fig.10: Two realizations of first-stage for n = 7



Fig. 11: Second-stage



Fig. 12 Third-stage





Fig. 14: Module(16)



4.1.4 Designing for odd values of n

In this case, we first design the Module(n+1). Then, we set one variable to logic 0 and remove the affected logic cells in Module(n+1) to realize Module(n). These logic cells are removed only from the 1st stage.

Example 7: Module(7) is obtained from Module(8) of Fig. 13b by removing one variable and some cells. We can realize it in two ways as shown in Figs. 15a and 15b.

4.1.5 Hardware cost and delay

Let C(n) denote the number of 2-input cells in Module(n). Then C(n) \leq nlog n + 2C(n/2) + O(n). Hence, C(n) = $O(n\log^2 n)$.

Circuit delay

We assume unit gate delay through a 2-input gate. For an n-input function, the minimum delay through the circuit is $\lceil \log(n) \rceil$, and for or $n = 2^k$, the maximum delay is (n - 1).

4.2 Synthesis of general symmetric functions

To synthesize a consecutive symmetric function which is not unate, we use the result stated in Theorem 1 that $S^n(a_1 - a_r)$ can be expressed as a composition of two unate symmetric functions.

Hence, $S^{n}(a_{l}-a_{r}) = u_{l}(n) \quad \overline{u_{r+1}}(n).$

The unate functions $u_l(n)$ and $u_{r+1}(n)$ are produced by the Module(n). The complete circuit is shown in Fig. 16a.

Example 9: $S^{6}(3,4)$ is realized as $S^{6}(3,4) = S^{6}(3-6) \overline{S}^{6}(5-6)$

= $u_3(3)$ $u_5(5)$. The circuit is shown in Fig. 16b.



Fig. 16: Realization of (a) $S^n(a_l - a_r)$ (b) $S^n(3,4)$

Since a non-consecutive symmetric function $S^n(A)$ can be expressed uniquely as a union of maximal consecutive symmetric functions, a general symmetric function can be realized by OR-ing together the outputs of constituent consecutive symmetric functions.

5. Experimental results

We compare the hardware cost and delay of the proposed design with a DSTL array [7]. For an n-input DSTL array, one has the following parameters:

(i) number of cells = n(n-1)/2;
(ii) minimum delay = n;
(iii) average delay = 0.5(3n-1);
(iv) maximum delay =2n - 1.

Table 1 shows that the number of cells (where each cell consists of two two-input gates) and circuit delay for our design compared to those in [7].

| Table 1: Cost and delay for realizing unate | 2 | | | | | | | |
|---|---|--|--|--|--|--|--|--|
| symmetric functions | | | | | | | | |

| n | # c | ells | delay | | | | | |
|----|--------|----------|-----------|------|-----|-----|----------|------|
| | As | Proposed | As in [7] | | | Pro | posed Me | thod |
| | | | | | | | | |
| | in [7] | Method | Min | Avg | Max | Min | Avg | Max |
| | | | | | | | | |
| 2 | 1 | 1 | 2 | 2.5 | 3 | 1 | 1 | 1 |
| 3 | 3 | 3 | 3 | 4 | 5 | 2 | 2.67 | 3 |
| 4 | 6 | 5 | 4 | 5.5 | 7 | 2 | 2.5 | 3 |
| 5 | 10 | 9 | 5 | 7 | 9 | 3 | 4.2 | 5 |
| 6 | 15 | 12 | 6 | 8.5 | 11 | 3 | 4 | 5 |
| 7 | 21 | 16 | 7 | 10 | 13 | 3 | 5.57 | 7 |
| 8 | 28 | 19 | 8 | 11.5 | 15 | 3 | 5.25 | 7 |
| 9 | 36 | 29 | 9 | 13 | 17 | 4 | 10.44 | 10 |
| 10 | 45 | 32 | 10 | 14.5 | 19 | 4 | 9.8 | 10 |
| 11 | 55 | 43 | 11 | 16 | 21 | 4 | 9.09 | 12 |
| 12 | 66 | 47 | 12 | 17.5 | 23 | 4 | 8.67 | 12 |
| 13 | 78 | 54 | 13 | 19 | 25 | 4 | 9.69 | 13 |
| 14 | 91 | 58 | 14 | 20.5 | 27 | 4 | 9.28 | 13 |
| 15 | 105 | 71 | 15 | 22 | 29 | 4 | 11.07 | 15 |
| 16 | 120 | 75 | 16 | 23.5 | 31 | 4 | 10.63 | 15 |
| | | 1 1 | 1 | 1 | | | | |

For general consecutive symmetric functions, we compare hardware cost with those in [2] and [3] in terms of the number of gate inputs (Table 2). The results show a drastic reduction in cost. While these earlier methods use fixed number of logic levels, for instance, at most 4 [2], or at most 5 [3], the proposed method reduces logic significantly at the cost of increasing the number of logic levels.

6. Conclusion

We have introduced a new technique for synthesizing a symmetric function using a cellular structure. The proposed module for realizing unate symmetric functions needs less hardware and delay compared to a DSTL array. For general symmetric functions, our synthesis method based on unate decomposition yields very low cost circuits compared to earlier methods [2, 3]. Testability issues of this design, and extending the technique for synthesizing an arbitrary Boolean function by multi-threshold partitioning [8], will be reported in a future work.

| Functions | Number of gate inputs | | | | | |
|--|--|--|---|--|--|--|
| $S^n(a_l-a_r)$ | As in [2] | As in [3] | Proposed Method | | | |
| $\begin{tabular}{ c c c c c } \hline Functions \\ \hline $S^n(a_l-a_r) \\ \hline $S^5(2,3) \\ $S^5(1,2) \\ $S^6(4,5) \\ $S^6(1,2) \\ $S^6(4,5) \\ $S^6(2,3) \\ $S^7(1,5) \\ $S^7(1,2) \\ $S^8(2,6) \\ $$ | Number of As in [2] 47 50 47 83 83 112 112 219 72 135 245 219 394 140 394 520 520 1010 410 662 1134 100 662 1134 100 662 1134 1010 1832 840 1832 2354 2354 2354 2354 2355 8318 4455 8318 10430 10430 20165 10584 1445 22308 20165 37039 22022 237039 | of gate input As in [3] 32 38 32 56 56 73 138 42 83 150 138 228 306 566 217 381 656 1009 466 1009 466 1009 466 1009 466 1009 466 1009 466 1009 466 1009 466 1009 4330 2340 4330 5463 10261 18596 11262 18596 | tts Proposed Method 38 38 38 50 50 50 50 50 50 50 66 66 66 66 66 66 66 66 66 66 66 78 78 78 78 78 78 78 78 78 78 78 78 118 118 118 118 130 | | | |
| $ \begin{array}{c} S^{14}(7,8) \\ S^{14}(6,7) \\ S^{15}(8,9) \\ S^{15}(5-9) \\ S^{15}(5,6) \\ S^{15}(7,8) \\ S^{15}(6,7) \end{array} $ | 45476 45476 87947 50052 65067 96525 87947 | 22877 22877 43198 24671 32312 47950 43198 | 234 234 334 286 286 286 286 | | | |
| | 1 | | | | | |

Table 2: Cost of general symmetric functions

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