producerConsumer

Tight Rope v0.75

4th October 2016

1 ID Files

1.1 MissionIds

section *MissionIds* **parents** *scj_prelude*, *MissionId*

$$MainMissionMID : MissionID$$
$$TakeOffMissionMID : MissionID$$
$$CruiseMissionMID : MissionID$$
$$LandMissionMID : MissionID$$

$$distinct\langle nullMissionId, MainMissionMID, TakeOffMissionMID, CruiseMissionMID, LandMissionMID\rangle$$

1.2 SchedulablesIds

section *SchedulableIds* **parents** *scj_prelude*, *SchedulableId*

$$
\begin{array}{l}
MainMissionSequencerSID : SchedulableID \\
ACModeChangerSID : SchedulableID \\
EnvironmentMonitorSID : SchedulableID \\
ControlHandlerSID : SchedulableID \\
FlightSensorsMonitorSID : SchedulableID \\
CommunicationsHandlerSID : SchedulableID \\
AperiodicSimulatorSID : SchedulableID \\
LandingGearHandlerTakeOffSID : SchedulableID \\
TakeOffMonitorSID : SchedulableID \\
TakeOffFailureHandlerSID : SchedulableID \\
BeginLandingHandlerSID : SchedulableID \\
NavigationMonitorSID : SchedulableID \\
GroundDistanceMonitorSID : SchedulableID \\
LandingGearHandlerLandSID : SchedulableID \\
InstrumentLandingSystemMonitorSID : SchedulableID \\
SafeLandingHandlerSID : SchedulableID \\
\hline
distinct\langle nullSequencerId, nullSchedulableId, MainMissionSequencerSID, \\
ACModeChangerSID, EnvironmentMonitorSID, \\
ControlHandlerSID, FlightSensorsMonitorSID, \\
CommunicationsHandlerSID, AperiodicSimulatorSID, \\
LandingGearHandlerTakeOffSID, TakeOffMonitorSID, \\
TakeOffFailureHandlerSID, BeginLandingHandlerSID, \\
NavigationMonitorSID, GroundDistanceMonitorSID, \\
LandingGearHandlerLandSID, InstrumentLandingSystemMonitorSID, \\
SafeLandingHandlerSID\rangle
\end{array}
$$

1.3 ThreadIds

section *ThreadIds* **parents** *scj_prelude*, *GlobalTypes*

$$
\begin{array}{l}
InstrumentLandingSystemMonitorTID : ThreadID \\
SafeLandingHandlerTID : ThreadID \\
GroundDistanceMonitorTID : ThreadID \\
CommunicationsHandlerTID : ThreadID \\
ControlHandlerTID : ThreadID \\
AperiodicSimulatorTID : ThreadID \\
TakeOffFailureHandlerTID : ThreadID \\
LandingGearHandlerLandTID : ThreadID \\
EnvironmentMonitorTID : ThreadID \\
FlightSensorsMonitorTID : ThreadID \\
NavigationMonitorTID : ThreadID \\
ACModeChangerTID : ThreadID \\
BeginLandingHandlerTID : ThreadID \\
LandingGearHandlerTakeOffTID : ThreadID \\
TakeOffMonitorTID : ThreadID
\end{array}
$$

$$
\begin{array}{l}
distinct\langle SafeletTId, nullThreadId, \\
InstrumentLandingSystemMonitorTID, SafeLandingHandlerTID, \\
GroundDistanceMonitorTID, CommunicationsHandlerTID, \\
ControlHandlerTID, AperiodicSimulatorTID, \\
TakeOffFailureHandlerTID, LandingGearHandlerLandTID, \\
EnvironmentMonitorTID, FlightSensorsMonitorTID, \\
NavigationMonitorTID, ACModeChangerTID, \\
BeginLandingHandlerTID, LandingGearHandlerTakeOffTID, \\
TakeOffMonitorTID\rangle
\end{array}
$$

1.4 ObjectIds

section *ObjectIds* **parents** *scj_prelude*, *GlobalTypes*

$$TakeOffMissionOID : ObjectID$$
$$LandMissionOID : ObjectID$$

$$distinct\langle TakeOffMissionOID, LandMissionOID\rangle$$

2 Network

2.1 Network Channel Sets

section *NetworkChannels* **parents** *scj_prelude*, *MissionId*, *MissionIds*, *SchedulableId*, *SchedulableIds*, *MissionChan*, *TopLevelMissionSequencerFWChan*, *FrameworkChan*, *SafeletChan*, *AperiodicEventHandlerChan*, *ManagedThreadChan*, *OneShotEventHandlerChan*, *PeriodicEventHandlerChan*, *MissionSequencerMethChan*

channelset *TerminateSync* ==
{| *schedulables_terminated*, *schedulables_stopped*, *get_activeSchedulables* |}

channelset *ControlTierSync* ==
{| *start_toplevel_sequencer*, *done_toplevel_sequencer*, *done_safeletFW* |}

channelset *TierSync* ==
{| *start_mission* . *MainMission*, *done_mission* . *MainMission*, *done_safeletFW*, *done_toplevel_sequencer* |}

channelset *MissionSync* ==
{| *done_safeletFW*, *done_toplevel_sequencer*, *register*, *signalTerminationCall*, *signalTerminationRet*, *activate_schedulables*, *done_schedulable*, *cleanupSchedulableCall*, *cleanupSchedulableRet* |}

channelset *SchedulablesSync* ==
{| *activate_schedulables*, *done_safeletFW*, *done_toplevel_sequencer* |}

channelset *ClusterSync* ==
{| *done_toplevel_sequencer*, *done_safeletFW* |}

channelset *SafeltAppSync* $\widehat{=}$
{| *getSequencerCall*, *getSequencerRet*, *initializeApplicationCall*, *initializeApplicationRet*, *end_safelet_app* |}

channelset *MissionSequencerAppSync* ==
{| *getNextMissionCall*, *getNextMissionRet*, *end_sequencer_app* |}

channelset *MissionAppSync* ==
{| *initializeCall*, *register*, *initializeRet*, *cleanupMissionCall*, *cleanupMissionRet* |}

channelset *AppSync* ==
$\bigcup\{$*SafeltAppSync*, *MissionSequencerAppSync*, *MissionAppSync*, *MTAppSync*, *OSEHSync*, *APEHSync*, *PEHSync*, {| *getSequencer*, *end_mission_app*, *end_managedThread_app*, *setCeilingPriority*, *requestTerminationCall*, *requestTerminationRet*, *terminationPendingCall*, *terminationPendingRet*, *handleAsyncEventCall*, *handleAsyncEventRet* |}$\}$

channelset *ThreadSync* ==
{| *raise_thread_priority*, *lower_thread_priority*, *isInterruptedCall*, *isInterruptedRet*, *get_priorityLevel* |}

channelset *LockingSync* ==
{| *lockAcquired*, *startSyncMeth*, *endSyncMeth*, *waitCall*, *waitRet*, *notify*, *isInterruptedCall*, *isInterruptedRet*, *interruptedCall*, *interruptedRet*, *done_toplevel_sequencer*, *get_priorityLevel* |}

channelset $Tier0Sync ==$
$\{\!|\ done\_toplevel\_sequencer, done\_safeletFW,$
$start\_mission\ .\ TakeOffMission, done\_mission\ .\ TakeOffMission,$
$initializeRet\ .\ TakeOffMission, requestTermination\ .\ TakeOffMission\ .\ MainMissionSequencer,$
$start\_mission\ .\ CruiseMission, done\_mission\ .\ CruiseMission,$
$initializeRet\ .\ CruiseMission, requestTermination\ .\ CruiseMission\ .\ MainMissionSequencer,$
$start\_mission\ .\ LandMission, done\_mission\ .\ LandMission,$
$initializeRet\ .\ LandMission, requestTermination\ .\ LandMission\ .\ MainMissionSequencer\ |\!\}$

2.2 MethodCallBinder

section *MethodCallBindingChannels* **parents** *scj_prelude*, *GlobalTypes*, *FrameworkChan*, *MissionId*, *MissionIds*, *SchedulableId*, *SchedulableIds*, *ThreadIds*

channel $binder\_getAltitudeCall : MissionID \times SchedulableID$
channel $binder\_getAltitudeRet : MissionID \times SchedulableID \times \mathbb{P}\,\mathbb{A}$

$getAltitudeLocs == \{MainMissionMID\}$
$getAltitudeCallers ==$
$\{NavigationMonitorSID, TakeOffMonitorSID, GroundDistanceMonitorSID, SafeLandingHandlerSID\}$

channel $binder\_stowLandingGearCall : MissionID \times SchedulableID$
channel $binder\_stowLandingGearRet : MissionID \times SchedulableID$

$stowLandingGearLocs == \{TakeOffMissionMID, LandMissionMID\}$
$stowLandingGearCallers == \{LandingGearHandlerTakeOffSID, LandingGearHandlerLandSID\}$

channel $binder\_getHeadingCall : MissionID \times SchedulableID$
channel $binder\_getHeadingRet : MissionID \times SchedulableID \times \mathbb{P}\,\mathbb{A}$

$getHeadingLocs == \{MainMissionMID\}$
$getHeadingCallers == \{NavigationMonitorSID\}$

channel $binder\_getAirSpeedCall : MissionID \times SchedulableID$
channel $binder\_getAirSpeedRet : MissionID \times SchedulableID \times \mathbb{P}\,\mathbb{A}$

$getAirSpeedLocs == \{MainMissionMID\}$
$getAirSpeedCallers == \{NavigationMonitorSID, TakeOffFailureHandlerSID\}$

channel $binder\_deployLandingGearCall : MissionID \times SchedulableID \times ThreadID$
channel $binder\_deployLandingGearRet : MissionID \times SchedulableID \times ThreadID$

$deployLandingGearLocs == \{TakeOffMissionMID, LandMissionMID\}$
$deployLandingGearCallers ==$
$\{LandingGearHandlerTakeOffSID, LandingGearHandlerLandSID\}$

channel $binder\_isLandingGearDeployedCall : MissionID \times SchedulableID$
channel $binder\_isLandingGearDeployedRet : MissionID \times SchedulableID \times \mathbb{B}$

$isLandingGearDeployedLocs == \{TakeOffMissionMID, LandMissionMID\}$
$isLandingGearDeployedCallers == \{LandingGearHandlerTakeOffSID, LandingGearHandlerLandSID\}$

channelset $MethodCallBinderSync == \{\!|\ done\_toplevel\_sequencer,$
$binder\_getAltitudeCall, binder\_getAltitudeRet,$
$binder\_stowLandingGearCall, binder\_stowLandingGearRet,$
$binder\_getHeadingCall, binder\_getHeadingRet,$
$binder\_getAirSpeedCall, binder\_getAirSpeedRet,$
$binder\_deployLandingGearCall, binder\_deployLandingGearRet,$
$binder\_isLandingGearDeployedCall, binder\_isLandingGearDeployedRet\ |\!\}$

section $MethodCallBinder$ **parents** $scj\_prelude, MissionId, MissionIds,$
$SchedulableId, SchedulableIds, MethodCallBindingChannels$
$, MainMissionMethChan, LandMissionMethChan$

process $MethodCallBinder \mathrel{\widehat=}$ **begin**

$$getAltitude\_MethodBinder \mathrel{\widehat=} \left(\begin{array}{l} binder\_getAltitudeCall\,?\,loc : (loc \in getAltitudeLocs)\,?\,caller : (caller \in getAltitudeCallers) \longrightarrow \\ getAltitudeCall\,.\,loc\,.\,caller \longrightarrow \\ getAltitudeRet\,.\,loc\,.\,caller\,?\,ret \longrightarrow \\ binder\_getAltitudeRet\,.\,loc\,.\,caller\,!\,ret \longrightarrow \\ getAltitude\_MethodBinder \end{array}\right)$$

$$stowLandingGear\_MethodBinder \mathrel{\widehat=} \left(\begin{array}{l} binder\_stowLandingGearCall \\ \quad ?\,loc : (loc \in stowLandingGearLocs) \\ \quad ?\,caller : (caller \in stowLandingGearCallers) \longrightarrow \\ stowLandingGearCall\,.\,loc\,.\,caller \longrightarrow \\ stowLandingGearRet\,.\,loc\,.\,caller \longrightarrow \\ binder\_stowLandingGearRet\,.\,loc\,.\,caller \longrightarrow \\ stowLandingGear\_MethodBinder \end{array}\right)$$

$$getHeading\_MethodBinder \mathrel{\widehat=} \left(\begin{array}{l} binder\_getHeadingCall\,?\,loc : (loc \in getHeadingLocs)\,?\,caller : (caller \in getHeadingCallers) \longrightarrow \\ getHeadingCall\,.\,loc\,.\,caller \longrightarrow \\ getHeadingRet\,.\,loc\,.\,caller\,?\,ret \longrightarrow \\ binder\_getHeadingRet\,.\,loc\,.\,caller\,!\,ret \longrightarrow \\ getHeading\_MethodBinder \end{array}\right)$$

$$getAirSpeed\_MethodBinder \mathrel{\widehat=} \left(\begin{array}{l} binder\_getAirSpeedCall \\ \quad ?\,loc : (loc \in getAirSpeedLocs) \\ quad\,?\,caller : (caller \in getAirSpeedCallers) \longrightarrow \\ getAirSpeedCall\,.\,loc\,.\,caller \longrightarrow \\ getAirSpeedRet\,.\,loc\,.\,caller\,?\,ret \longrightarrow \\ binder\_getAirSpeedRet\,.\,loc\,.\,caller\,!\,ret \longrightarrow \\ getAirSpeed\_MethodBinder \end{array}\right)$$

$$deployLandingGear\_MethodBinder \mathrel{\widehat=} \left(\begin{array}{l} binder\_deployLandingGearCall \\ \quad ?\,loc : (loc \in deployLandingGearLocs) \\ \quad ?\,caller : (caller \in deployLandingGearCallers)\,?\,callingThread \longrightarrow \\ deployLandingGearCall\,.\,loc\,.\,caller\,.\,callingThread \longrightarrow \\ deployLandingGearRet\,.\,loc\,.\,caller\,.\,callingThread \longrightarrow \\ binder\_deployLandingGearRet\,.\,loc\,.\,caller\,.\,callingThread \longrightarrow \\ deployLandingGear\_MethodBinder \end{array}\right)$$

$isLandingGearDeployed\_MethodBinder \mathrel{\widehat{=}}$

$$\left(\begin{array}{l} binder\_isLandingGearDeployedCall \\ \quad ?\, loc : (loc \in isLandingGearDeployedLocs) \\ \quad ?\, caller : (caller \in isLandingGearDeployedCallers) \longrightarrow \\ isLandingGearDeployedCall\,.\,loc\,.\,caller \longrightarrow \\ isLandingGearDeployedRet\,.\,loc\,.\,caller\,?\,ret \longrightarrow \\ binder\_isLandingGearDeployedRet\,.\,loc\,.\,caller\,!\,ret \longrightarrow \\ isLandingGearDeployed\_MethodBinder \end{array}\right)$$

$BinderActions \mathrel{\widehat{=}}$

$$\left(\begin{array}{l} getAltitude\_MethodBinder \\ \|\| \\ stowLandingGear\_MethodBinder \\ \|\| \\ getHeading\_MethodBinder \\ \|\| \\ getAirSpeed\_MethodBinder \\ \|\| \\ deployLandingGear\_MethodBinder \\ \|\| \\ isLandingGearDeployed\_MethodBinder \end{array}\right)$$

- $BinderActions \triangle (done\_toplevel\_sequencer \longrightarrow \mathbf{Skip})$

end

2.3 Locking

section *NetworkLocking* **parents** *scj_prelude*, *GlobalTypes*, *FrameworkChan*, *MissionId*, *MissionIds*, *ThreadIds*, *NetworkChannels*, *ObjectFW*, *ThreadFW*

process $Threads \mathrel{\widehat=}$
$$\left(\begin{array}{l} ThreadFW(InstrumentLandingSystemMonitorTID, 5) \\ ||| \\ ThreadFW(SafeLandingHandlerTID, 5) \\ ||| \\ ThreadFW(GroundDistanceMonitorTID, 5) \\ ||| \\ ThreadFW(CommunicationsHandlerTID, 5) \\ ||| \\ ThreadFW(ControlHandlerTID, 5) \\ ||| \\ ThreadFW(AperiodicSimulatorTID, 5) \\ ||| \\ ThreadFW(TakeOffFailureHandlerTID, 5) \\ ||| \\ ThreadFW(LandingGearHandlerLandTID, 5) \\ ||| \\ ThreadFW(EnvironmentMonitorTID, 5) \\ ||| \\ ThreadFW(FlightSensorsMonitorTID, 5) \\ ||| \\ ThreadFW(NavigationMonitorTID, 5) \\ ||| \\ ThreadFW(ACModeChangerTID, 5) \\ ||| \\ ThreadFW(BeginLandingHandlerTID, 5) \\ ||| \\ ThreadFW(LandingGearHandlerTakeOffTID, 5) \\ ||| \\ ThreadFW(TakeOffMonitorTID, 5) \end{array}\right)$$

process $Objects \mathrel{\widehat=}$
$$\left(\begin{array}{l} ObjectFW(TakeOffMissionOID) \\ ||| \\ ObjectFW(LandMissionOID) \end{array}\right)$$

process $Locking \mathrel{\widehat=} Threads \llbracket ThreadSync \rrbracket Objects$

2.4 Program

section *Program* **parents** *scj_prelude*, *MissionId*, *MissionIds*,
SchedulableId, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *MissionFW*,
SafeletFW, *TopLevelMissionSequencerFW*, *NetworkChannels*, *ManagedThreadFW*,
SchedulableMissionSequencerFW, *PeriodicEventHandlerFW*, *OneShotEventHandlerFW*,
AperiodicEventHandlerFW, *ObjectFW*, *ThreadFW*,
ACSafeletApp, *MainMissionSequencerApp*, *MainMissionApp*, *ACModeChangerApp*
, *ControlHandlerApp*,
CommunicationsHandlerApp, *EnvironmentMonitorApp*, *FlightSensorsMonitorApp*,
AperiodicSimulatorApp, *TakeOffMissionApp*, *LandingGearHandlerTakeOffApp*
, *TakeOffFailureHandlerApp*
,
TakeOffMonitorApp, *CruiseMissionApp*, *BeginLandingHandlerApp*, *NavigationMonitorApp*
, *LandMissionApp*, *LandingGearHandlerLandApp*, *SafeLandingHandlerApp*
, *GroundDistanceMonitorApp*,
InstrumentLandingSystemMonitorApp

process $ControlTier \mathrel{\widehat=}$

$$\left(\begin{array}{l} SafeletFW \\ \quad [\![ControlTierSync]\!] \\ TopLevelMissionSequencerFW(MainMissionSequencer) \end{array}\right)$$

process $Tier0 \mathrel{\widehat=}$

$$\left(\begin{array}{l} MissionFW(MainMissionID) \\ \quad [\![MissionSync]\!] \\ \left(\begin{array}{l} SchedulableMissionSequencerFW(ACModeChangerID) \\ \quad [\![SchedulablesSync]\!] \\ \left(\begin{array}{l} AperiodicEventHandlerFW(ControlHandlerID, (time(10,0), null)) \\ \quad [\![SchedulablesSync]\!] \\ AperiodicEventHandlerFW(CommunicationsHandlerID, (NULL, nullSchedulableId)) \end{array}\right) \\ \quad [\![SchedulablesSync]\!] \\ \left(\begin{array}{l} PeriodicEventHandlerFW(EnvironmentMonitorID, \\ \quad (time(10,0), NULL, NULL, nullSchedulableId)) \\ \quad [\![SchedulablesSync]\!] \\ PeriodicEventHandlerFW(FlightSensorsMonitorID, \\ \quad (time(10,0), NULL, NULL, nullSchedulableId)) \\ \quad [\![SchedulablesSync]\!] \\ PeriodicEventHandlerFW(AperiodicSimulatorID, \\ \quad (time(10,0), NULL, NULL, nullSchedulableId)) \end{array}\right) \end{array}\right) \end{array}\right)$$

$$
\begin{array}{l}
\textbf{process}\ Tier1 \mathrel{\widehat{=}} \\
\left(\begin{array}{l}
MissionFW(TakeOffMissionID) \\
\quad [\![MissionSync]\!] \\
\left(\begin{array}{l}
\left(\begin{array}{l}
AperiodicEventHandlerFW(LandingGearHandlerTakeOffID, (NULL, nullSchedulableId)) \\
\quad [\![SchedulablesSync]\!] \\
AperiodicEventHandlerFW(TakeOffFailureHandlerID, (NULL, nullSchedulableId))
\end{array}\right) \\
PeriodicEventHandlerFW(TakeOffMonitorID, (time(0,0), time(500,0), NULL, nullSchedulableId))
\end{array}\right)
\end{array}\right) \\
\quad [\![ClusterSync]\!] \\
\left(\begin{array}{l}
MissionFW(CruiseMissionID) \\
\quad [\![MissionSync]\!] \\
\left(\begin{array}{l}
AperiodicEventHandlerFW(BeginLandingHandlerID, (NULL, nullSchedulableId)) \\
\quad [\![SchedulablesSync]\!] \\
PeriodicEventHandlerFW(NavigationMonitorID, (time(0,0), time(10,0), NULL, nullSchedulableId))
\end{array}\right)
\end{array}\right) \\
\quad [\![ClusterSync]\!] \\
\left(\begin{array}{l}
MissionFW(LandMissionID) \\
\quad [\![MissionSync]\!] \\
\left(\begin{array}{l}
\left(\begin{array}{l}
AperiodicEventHandlerFW(LandingGearHandlerLandID, (NULL, nullSchedulableId)) \\
\quad [\![SchedulablesSync]\!] \\
AperiodicEventHandlerFW(SafeLandingHandlerID, (NULL, nullSchedulableId))
\end{array}\right) \\
\quad [\![SchedulablesSync]\!] \\
\left(\begin{array}{l}
PeriodicEventHandlerFW(GroundDistanceMonitorID, \\
\quad (time(0,0), time(10,0), NULL, nullSchedulableId)) \\
\quad [\![SchedulablesSync]\!] \\
PeriodicEventHandlerFW(InstrumentLandingSystemMonitorID, \\
\quad (time(0,0), time(10,0), NULL, nullSchedulableId))
\end{array}\right)
\end{array}\right)
\end{array}\right)
\end{array}
$$

$$
\begin{array}{l}
\textbf{process}\ Framework \mathrel{\widehat{=}} \\
\left(\begin{array}{l}
ControlTier \\
\quad [\![TierSync]\!] \\
\left(\begin{array}{l}
Tier0 \\
\quad [\![Tier0Sync]\!] \\
Tier1
\end{array}\right)
\end{array}\right)
\end{array}
$$

process $Application \mathrel{\widehat{=}}$

$$
\begin{pmatrix}
ACSafeletApp \\
|||\\
MainMissionSequencerApp \\
|||\\
MainMissionApp \\
|||\\
ACModeChangerApp(MainMissionID) \\
|||\\
ControlHandlerApp \\
|||\\
CommunicationsHandlerApp \\
|||\\
EnvironmentMonitorApp(MainMissionID) \\
|||\\
FlightSensorsMonitorApp(MainMissionID) \\
|||\\
AperiodicSimulatorApp(controlHandlerID) \\
|||\\
TakeOffMissionApp \\
|||\\
LandingGearHandlerTakeOffApp(TakeOffMissionID) \\
|||\\
TakeOffFailureHandlerApp(MissionID, TakeOffMissionID, 10.0) \\
|||\\
TakeOffMonitorApp(MissionID, TakeOffMissionID, 10.0, landingGearHandlerID) \\
|||\\
CruiseMissionApp \\
|||\\
BeginLandingHandlerApp(MissionID) \\
|||\\
NavigationMonitorApp(MissionID) \\
|||\\
LandMissionApp \\
|||\\
LandingGearHandlerLandApp(LandMissionID) \\
|||\\
SafeLandingHandlerApp(MissionID, 10.0) \\
|||\\
GroundDistanceMonitorApp(MissionID) \\
|||\\
InstrumentLandingSystemMonitorApp(LandMissionID)
\end{pmatrix}
$$

process $Program \mathrel{\widehat{=}} \big(Framework \llbracket\ AppSync\ \rrbracket\ ApplicationB\big) \llbracket\ LockingSync\ \rrbracket\ Locking$

3 Safelet

section *ACSafeletApp* **parents** *scj_prelude*, *SchedulableId*, *SchedulableIds*, *SafeletChan*, *MethodCallBindingChannels*

process $ACSafeletApp \mathrel{\widehat=} \textbf{begin}$

$$InitializeApplication \mathrel{\widehat=} \begin{pmatrix} initializeApplicationCall \longrightarrow \\ initializeApplicationRet \longrightarrow \\ \textbf{Skip} \end{pmatrix}$$

$$GetSequencer \mathrel{\widehat=} \begin{pmatrix} getSequencerCall \longrightarrow \\ getSequencerRet\,!\,MainMissionSequencerSID \longrightarrow \\ \textbf{Skip} \end{pmatrix}$$

$$Methods \mathrel{\widehat=} \begin{pmatrix} GetSequencer \\ \Box \\ InitializeApplication \end{pmatrix} ;\ Methods$$

$\bullet\ (Methods) \triangle (end\_safelet\_app \longrightarrow \textbf{Skip})$

end

4 Top Level Mission Sequencer

section *MainMissionSequencerApp* **parents** *TopLevelMissionSequencerChan*, *MissionId*, *MissionIds*, *SchedulableId*, *SchedulableIds*, *MainMissionSequencerClass*, *MethodCallBindingChannels*

process $MainMissionSequencerApp \mathrel{\widehat=} \textbf{begin}$

State

$this : \textbf{ref}\ MainMissionSequencerClass$

state *State*

Init

$State'$

$this' = \textbf{new}\ MainMissionSequencerClass()$

$GetNextMission \mathrel{\widehat=} \textbf{var}\ ret : MissionID \bullet$
$\left(\begin{array}{l} getNextMissionCall\,.\,MainMissionSequencerSID \longrightarrow \\ ret := this\,.\,getNextMission(); \\ getNextMissionRet\,.\,MainMissionSequencerSID\,!\,ret \longrightarrow \\ \textbf{Skip} \end{array}\right)$

$Methods \mathrel{\widehat=}$
$\big(GetNextMission\big)\ ;\ Methods$

$\bullet\ (Init\ ;\ Methods) \triangle (end\_sequencer\_app\,.\,MainMissionSequencerSID \longrightarrow \textbf{Skip})$

end

section *MainMissionSequencerClass* **parents** *scj_prelude*, *SchedulableId*, *SchedulableIds*, *SafeletChan*, *MethodCallBindingChannels*, *MissionId*, *MissionIds*

class *MainMissionSequencerClass* $\widehat{=}$ **begin**

state *State*

$$returnedMission : \mathbb{B}$$

state *State*

initial *Init*

$$State'$$

$$returnedMission' = \mathbf{False}$$

protected *getNextMission* $\widehat{=}$ **var** *ret* : *MissionID* $\bullet$

$$\left(\begin{array}{l} \mathbf{if}\ (\neg\ returnedMission = \mathbf{True}) \longrightarrow \\ \qquad \left(\begin{array}{l} this\ .\ returnedMission := \mathbf{True}; \\ ret := MainMissionMID \end{array}\right) \\ [\!]\ \neg\ (\neg\ returnedMission = \mathbf{True}) \longrightarrow \\ \qquad \big(ret := nullMissionId\big) \\ \mathbf{fi} \end{array}\right)$$

$\bullet$ **Skip**

end

5 Missions

5.1 MainMission

section *MainMissionApp* **parents** *scj_prelude*, *MissionId*, *MissionIds*, *SchedulableId*, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *MainMissionMethChan*, *MainMissionClass*, *MethodCallBindingChannels*

process $MainMissionApp \mathrel{\widehat=}$ **begin**

State

$this : \mathbf{ref}\ MainMissionClass$

state *State*

Init

$State'$

$this' = \mathbf{new}\ MainMissionClass()$

$InitializePhase \mathrel{\widehat=}$
$\left(\begin{array}{l} initializeCall\,.\,MainMissionMID \longrightarrow \\ register\,!\,ACModeChangerSID\,!\,MainMissionMID \longrightarrow \\ register\,!\,EnvironmentMonitorSID\,!\,MainMissionMID \longrightarrow \\ register\,!\,ControlHandlerSID\,!\,MainMissionMID \longrightarrow \\ register\,!\,FlightSensorsMonitorSID\,!\,MainMissionMID \longrightarrow \\ register\,!\,CommunicationsHandlerSID\,!\,MainMissionMID \longrightarrow \\ register\,!\,AperiodicSimulatorSID\,!\,MainMissionMID \longrightarrow \\ initializeRet\,.\,MainMissionMID \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$CleanupPhase \mathrel{\widehat=}$
$\left(\begin{array}{l} cleanupMissionCall\,.\,MainMissionMID \longrightarrow \\ cleanupMissionRet\,.\,MainMissionMID\,!\,\mathbf{True} \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$getAirSpeedMeth \mathrel{\widehat=} \mathbf{var}\ ret : \mathbb{P}\,\mathbb{A} \bullet$
$\left(\begin{array}{l} getAirSpeedCall\,.\,MainMissionMID\,?\,caller \longrightarrow \\ ret := this\,.\,getAirSpeed(); \\ getAirSpeedRet\,.\,MainMissionMID\,.\,caller\,!\,ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$getAltitudeMeth \mathrel{\widehat=} \mathbf{var}\ ret : \mathbb{P}\,\mathbb{A} \bullet$
$\left(\begin{array}{l} getAltitudeCall\,.\,MainMissionMID\,?\,caller \longrightarrow \\ ret := this\,.\,getAltitude(); \\ getAltitudeRet\,.\,MainMissionMID\,.\,caller\,!\,ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$getCabinPressureMeth \mathrel{\widehat=} \mathbf{var}\ ret : \mathbb{P}\,\mathbb{A} \bullet$
$\left(\begin{array}{l} getCabinPressureCall\,.\,MainMissionMID \longrightarrow \\ ret := this\,.\,getCabinPressure(); \\ getCabinPressureRet\,.\,MainMissionMID\,!\,ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$$getEmergencyOxygenMeth \mathrel{\widehat=} \textbf{var}\ ret : \mathbb{P}\,\mathbb{A} \bullet \left(\begin{array}{l} getEmergencyOxygenCall\,.\,MainMissionMID \longrightarrow \\ ret := this\,.\,getEmergencyOxygen(); \\ getEmergencyOxygenRet\,.\,MainMissionMID\,!\,ret \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$getFuelRemainingMeth \mathrel{\widehat=} \textbf{var}\ ret : \mathbb{P}\,\mathbb{A} \bullet \left(\begin{array}{l} getFuelRemainingCall\,.\,MainMissionMID \longrightarrow \\ ret := this\,.\,getFuelRemaining(); \\ getFuelRemainingRet\,.\,MainMissionMID\,!\,ret \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$getHeadingMeth \mathrel{\widehat=} \textbf{var}\ ret : \mathbb{P}\,\mathbb{A} \bullet \left(\begin{array}{l} getHeadingCall\,.\,MainMissionMID\,?\,caller \longrightarrow \\ ret := this\,.\,getHeading(); \\ getHeadingRet\,.\,MainMissionMID\,.\,caller\,!\,ret \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$setAirSpeedMeth \mathrel{\widehat=} \left(\begin{array}{l} setAirSpeedCall\,.\,MainMissionMID\,?\,airSpeed \longrightarrow \\ this\,.\,setAirSpeed(airSpeed); \\ setAirSpeedRet\,.\,MainMissionMID \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$setAltitudeMeth \mathrel{\widehat=} \left(\begin{array}{l} setAltitudeCall\,.\,MainMissionMID\,?\,altitude \longrightarrow \\ this\,.\,setAltitude(altitude); \\ setAltitudeRet\,.\,MainMissionMID \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$setCabinPressureMeth \mathrel{\widehat=} \left(\begin{array}{l} setCabinPressureCall\,.\,MainMissionMID\,?\,cabinPressure \longrightarrow \\ this\,.\,setCabinPressure(cabinPressure); \\ setCabinPressureRet\,.\,MainMissionMID \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$setEmergencyOxygenMeth \mathrel{\widehat=} \left(\begin{array}{l} setEmergencyOxygenCall\,.\,MainMissionMID\,?\,emergencyOxygen \longrightarrow \\ this\,.\,setEmergencyOxygen(emergencyOxygen); \\ setEmergencyOxygenRet\,.\,MainMissionMID \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$setFuelRemainingMeth \mathrel{\widehat=} \left(\begin{array}{l} setFuelRemainingCall\,.\,MainMissionMID\,?\,fuelRemaining \longrightarrow \\ this\,.\,setFuelRemaining(fuelRemaining); \\ setFuelRemainingRet\,.\,MainMissionMID \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$setHeadingMeth \mathrel{\widehat=} \left(\begin{array}{l} setHeadingCall\,.\,MainMissionMID\,?\,heading \longrightarrow \\ this\,.\,setHeading(heading); \\ setHeadingRet\,.\,MainMissionMID \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$Methods \mathrel{\widehat{=}} \left(\begin{array}{l} InitializePhase \\ \Box \\ CleanupPhase \\ \Box \\ getAirSpeedMeth \\ \Box \\ getAltitudeMeth \\ \Box \\ getCabinPressureMeth \\ \Box \\ getEmergencyOxygenMeth \\ \Box \\ getFuelRemainingMeth \\ \Box \\ getHeadingMeth \\ \Box \\ setAirSpeedMeth \\ \Box \\ setAltitudeMeth \\ \Box \\ setCabinPressureMeth \\ \Box \\ setEmergencyOxygenMeth \\ \Box \\ setFuelRemainingMeth \\ \Box \\ setHeadingMeth \end{array} \right) ; \; Methods$$

• $(Init \; ; \; Methods) \triangle (end\_mission\_app \,.\, MainMissionMID \longrightarrow \mathbf{Skip})$

end

section *MainMissionClass* **parents** *scj_prelude*, *SchedulableId*, *SchedulableIds*, *SafeletChan*
, *MethodCallBindingChannels*

class *MainMissionClass* $\widehat{=}$ **begin**

state *State*

$ALTITUDE\_READING\_ON\_GROUND : \mathbb{P}\,\mathbb{A}$
$cabinPressure : \mathbb{P}\,\mathbb{A}$
$emergencyOxygen : \mathbb{P}\,\mathbb{A}$
$fuelRemaining : \mathbb{P}\,\mathbb{A}$
$altitude : \mathbb{P}\,\mathbb{A}$
$airSpeed : \mathbb{P}\,\mathbb{A}$
$heading : \mathbb{P}\,\mathbb{A}$

state *State*

initial *Init*

$State'$

public *getAirSpeed* $\widehat{=}$ **var** $ret : \mathbb{P}\,\mathbb{A} \bullet$
$(ret := airSpeed)$

public *getAltitude* $\widehat{=}$ **var** $ret : \mathbb{P}\,\mathbb{A} \bullet$
$(ret := altitude)$

public *getCabinPressure* $\widehat{=}$ **var** $ret : \mathbb{P}\,\mathbb{A} \bullet$
$(ret := cabinPressure)$

public *getEmergencyOxygen* $\widehat{=}$ **var** $ret : \mathbb{P}\,\mathbb{A} \bullet$
$(ret := emergencyOxygen)$

public *getFuelRemaining* $\widehat{=}$ **var** $ret : \mathbb{P}\,\mathbb{A} \bullet$
$(ret := fuelRemaining)$

public *getHeading* $\widehat{=}$ **var** $ret : \mathbb{P}\,\mathbb{A} \bullet$
$(ret := heading)$

public *setAirSpeed* $\widehat{=}$
$(this\,.\,this.airSpeed := airSpeed)$

public *setAltitude* $\widehat{=}$
$(this\,.\,this.altitude := altitude)$

public *setCabinPressure* $\widehat{=}$
$(this\,.\,this.cabinPressure := cabinPressure)$

public $setEmergencyOxygen \mathrel{\widehat{=}}$
$\big(this\,.\,this.emergencyOxygen := emergencyOxygen\big)$

public $setFuelRemaining \mathrel{\widehat{=}}$
$\big(this\,.\,this.fuelRemaining := fuelRemaining\big)$

public $setHeading \mathrel{\widehat{=}}$
$\big(this\,.\,this.heading := heading\big)$

- **Skip**

end

5.2 Schedulables of MainMission

section $ACModeChangerApp$ **parents** $TopLevelMissionSequencerChan$,
$MissionId$, $MissionIds$, $SchedulableId$, $SchedulableIds$, $ACModeChangerClass$, $MethodCallBindingChannels$

process $ACModeChangerApp \mathrel{\widehat=}$
$controllingMission : MissionID \bullet$ **begin**

$$GetNextMission \mathrel{\widehat=} \textbf{var}\ ret : MissionID \bullet \left(\begin{array}{l} getNextMissionCall\,.\,ACModeChangerSID \longrightarrow \\ ret := this\,.\,getNextMission(); \\ getNextMissionRet\,.\,ACModeChangerSID\,!\,ret \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$Methods \mathrel{\widehat=} \big(GetNextMission\big)\ ;\ Methods$$

$$\bullet\ (Methods) \triangle (end\_sequencer\_app\,.\,ACModeChangerSID \longrightarrow \textbf{Skip})$$

end

section $ACModeChangerClass$ **parents** $scj\_prelude, SchedulableId, SchedulableIds, SafeletChan$, $MethodCallBindingChannels, MissionId, MissionIds$

class $ACModeChangerClass \mathrel{\widehat=}$ **begin**

state $State$

$controllingMission : MainMission$

$modesLeft : \mathbb{Z}$

state $State$

initial $Init$

$State'$

protected $getNextMission \mathrel{\widehat=}$ **var** $ret : MissionID \bullet$

$$
\left(\begin{array}{l}
\textbf{if } (modesLeft = 3) \longrightarrow \\
\quad \left(\begin{array}{l} modesLeft := modesLeft - 1; \\ ret := TakeOffMissionMID \end{array}\right) \\
[] \neg (modesLeft = 3) \longrightarrow \\
\quad \textbf{if } (modesLeft = 2) \longrightarrow \\
\quad \left(\begin{array}{l} modesLeft := modesLeft - 1; \\ ret := CruiseMissionMID \end{array}\right) \\
[] \neg (modesLeft = 2) \longrightarrow \\
\quad \textbf{if } (modesLeft = 1) \longrightarrow \\
\quad \left(\begin{array}{l} modesLeft := modesLeft - 1; \\ ret := LandMissionMID \end{array}\right) \\
[] \neg (modesLeft = 1) \longrightarrow \\
\quad \left(ret := nullMissionId\right) \\
\textbf{fi} \\
\textbf{fi} \\
\textbf{fi}
\end{array}\right)
$$

$\bullet$ **Skip**

end

section *ControlHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*, *MethodCallBindingChannels*

process $ControlHandlerApp \mathrel{\widehat=} \textbf{begin}$

$$handleAsyncEvent \mathrel{\widehat=} \left(\begin{array}{l} handleAsyncEventCall\,.\,ControlHandlerSID \longrightarrow \\ \textbf{Skip}; \\ handleAsyncEventRet\,.\,ControlHandlerSID \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$Methods \mathrel{\widehat=} \big(handleAsyncEvent\big)\ ;\ \ Methods$$

$$\bullet\ (Methods) \triangle (end\_aperiodic\_app\,.\,ControlHandlerSID \longrightarrow \textbf{Skip})$$

end

section *CommunicationsHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*, *MethodCallBindingChannels*

process $CommunicationsHandlerApp \mathrel{\widehat=} \textbf{begin}$

$$handleAsyncEvent \mathrel{\widehat=} \left(\begin{array}{l} handleAsyncEventCall\,.\,CommunicationsHandlerSID \longrightarrow \\ \textbf{Skip}; \\ handleAsyncEventRet\,.\,CommunicationsHandlerSID \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$Methods \mathrel{\widehat=} \big(handleAsyncEvent\big)\ ;\ \ Methods$$

$$\bullet\ (Methods) \triangle (end\_aperiodic\_app\,.\,CommunicationsHandlerSID \longrightarrow \textbf{Skip})$$

end

section *EnvironmentMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*, *MethodCallBindingChannels*

process $EnvironmentMonitorApp \mathrel{\widehat=}$
$mainMission : MissionID \bullet$ **begin**

$handleAsyncEvent \mathrel{\widehat=}$
$\begin{pmatrix} handleAsyncEventCall\,.\,EnvironmentMonitorSID \longrightarrow \\ \textbf{Skip}; \\ handleAsyncEventRet\,.\,EnvironmentMonitorSID \longrightarrow \\ \textbf{Skip} \end{pmatrix}$

$Methods \mathrel{\widehat=}$
$\big(handleAsyncEvent\big)\ ;\ Methods$

$\bullet\ (Methods) \triangle (end\_periodic\_app\,.\,EnvironmentMonitorSID \longrightarrow \textbf{Skip})$

end

section *EnvironmentMonitorClass* **parents** *scj_prelude*, *SchedulableId*, *SchedulableIds*, *SafeletChan*, *MethodCallBindingChannels*

class *EnvironmentMonitorClass* $\widehat{=}$ **begin**

state *State*

$controllingMission : MainMission$

state *State*

initial *Init*

$State'$

- **Skip**

end

section *FlightSensorsMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*, *MethodCallBindingChannels*

process $FlightSensorsMonitorApp \mathrel{\widehat=}$
$mainMission : MissionID \bullet$ **begin**

$handleAsyncEvent \mathrel{\widehat=}$
$\begin{pmatrix} handleAsyncEventCall\,.\,FlightSensorsMonitorSID \longrightarrow \\ \textbf{Skip}; \\ handleAsyncEventRet\,.\,FlightSensorsMonitorSID \longrightarrow \\ \textbf{Skip} \end{pmatrix}$

$Methods \mathrel{\widehat=}$
$\big(handleAsyncEvent\big)\ ;\ Methods$

$\bullet\ (Methods) \triangle (end\_periodic\_app\,.\,FlightSensorsMonitorSID \longrightarrow \textbf{Skip})$

end

section *FlightSensorsMonitorClass* **parents** *scj_prelude*, *SchedulableId*, *SchedulableIds*, *SafeletChan*, *MethodCallBindingChannels*

class *FlightSensorsMonitorClass* $\widehat{=}$ **begin**

state *State*

$controllingMission : MainMission$

state *State*

initial *Init*

$State'$

- **Skip**

end

5.3 TakeOffMission

section *TakeOffMissionApp* **parents** *scj_prelude*, *MissionId*, *MissionIds*, *SchedulableId*, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *TakeOffMissionMethChan*, *TakeOffMissionClass*, *MethodCallBindingChannels*, *ObjectFWChan*, *ObjectIds*

process $TakeOffMissionApp \mathrel{\widehat=}$
controllingMission : *MissionID* • **begin**

State

$this : \mathbf{ref}\ TakeOffMissionClass$

state *State*

Init

$State'$

$this' = \mathbf{new}\ TakeOffMissionClass()$

$InitializePhase \mathrel{\widehat=}$
$\left(\begin{array}{l} initializeCall\ .\ TakeOffMissionMID \longrightarrow \\ register\ !\ LandingGearHandlerTakeOffSID\ !\ TakeOffMissionMID \longrightarrow \\ register\ !\ TakeOffMonitorSID\ !\ TakeOffMissionMID \longrightarrow \\ register\ !\ TakeOffFailureHandlerSID\ !\ TakeOffMissionMID \longrightarrow \\ initializeRet\ .\ TakeOffMissionMID \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$CleanupPhase \mathrel{\widehat=}$
$\left(\begin{array}{l} cleanupMissionCall\ .\ TakeOffMissionMID \longrightarrow \\ cleanupMissionRet\ .\ TakeOffMissionMID\ !\ \mathbf{True} \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$takeOffAbortMeth \mathrel{\widehat=}$
$\left(\begin{array}{l} takeOffAbortCall\ .\ TakeOffMissionMID \longrightarrow \\ this\ .\ takeOffAbort(); \\ takeOffAbortRet\ .\ TakeOffMissionMID \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$cleanUpMeth \mathrel{\widehat=} \mathbf{var}\ ret : \mathbb{B} \bullet$
$\left(\begin{array}{l} cleanUpCall\ .\ TakeOffMissionMID \longrightarrow \\ ret := this\ .\ cleanUp(); \\ cleanUpRet\ .\ TakeOffMissionMID\ !\ ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$stowLandingGearMeth \mathrel{\widehat=}$
$\left(\begin{array}{l} stowLandingGearCall\ .\ TakeOffMissionMID\ ?\ caller \longrightarrow \\ this\ .\ stowLandingGear(); \\ stowLandingGearRet\ .\ TakeOffMissionMID\ .\ caller \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$$isLandingGearDeployedMeth \mathrel{\widehat=} \mathbf{var}\ ret : \mathbb{B} \bullet \left(\begin{array}{l} isLandingGearDeployedCall\ .\ TakeOffMissionMID\ ?\ caller \longrightarrow \\ ret := this\ .\ isLandingGearDeployed(); \\ isLandingGearDeployedRet\ .\ TakeOffMissionMID\ .\ caller\ !\ ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$$

$$deployLandingGearSyncMeth \mathrel{\widehat=} \left(\begin{array}{l} deployLandingGearCall\ .\ TakeOffMissionMID\ ?\ caller\ ?\ thread \longrightarrow \\ \left(\begin{array}{l} startSyncMeth\ .\ TakeOffMissionOID\ .\ thread \longrightarrow \\ lockAcquired\ .\ TakeOffMissionOID\ .\ thread \longrightarrow \\ \left(this\ .\ landingGearDeployed := \mathbf{True}\right); \\ endSyncMeth\ .\ TakeOffMissionOID\ .\ thread \longrightarrow \\ deployLandingGearRet\ .\ TakeOffMissionMID\ .\ caller\ .\ thread \longrightarrow \\ \mathbf{Skip} \end{array}\right) \end{array}\right)$$

$$Methods \mathrel{\widehat=} \left(\begin{array}{l} InitializePhase \\ \Box \\ CleanupPhase \\ \Box \\ takeOffAbortMeth \\ \Box \\ cleanUpMeth \\ \Box \\ stowLandingGearMeth \\ \Box \\ isLandingGearDeployedMeth \\ \Box \\ deployLandingGearSyncMeth \end{array}\right); \ Methods$$

$$\bullet\ (Init\ ;\ Methods) \triangle (end\_mission\_app\ .\ TakeOffMissionMID \longrightarrow \mathbf{Skip})$$

end

section *TakeOffMissionClass* **parents** *scj_prelude*, *SchedulableId*, *SchedulableIds*, *SafeletChan*
, *MethodCallBindingChannels*

class *TakeOffMissionClass* $\widehat{=}$ **begin**

state *State*

$SAFE\_AIRSPEED\_THRESHOLD : \mathbb{P}\,\mathbb{A}$
$TAKEOFF\_ALTITUDE : \mathbb{P}\,\mathbb{A}$
$controllingMission : MainMission$
$abort : \mathbb{B}$
$landingGearDeployed : \mathbb{B}$

state *State*

initial *Init*

$State'$

public *takeOffAbort* $\widehat{=}$
$\big(this\,.\,abort := \mathbf{True}\big)$

public *cleanUp* $\widehat{=}$ **var** $ret : \mathbb{B} \bullet$
$\big(ret := (\neg\ abort = \mathbf{True})\big)$

public *stowLandingGear* $\widehat{=}$
$\big(this\,.\,landingGearDeployed := \mathbf{False}\big)$

public *isLandingGearDeployed* $\widehat{=}$ **var** $ret : \mathbb{B} \bullet$
$\big(ret := landingGearDeployed = \mathbf{True}\big)$

• **Skip**

end

section *TakeOffMissionMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

channel $takeOffAbortCall : MissionID$
channel $takeOffAbortRet : MissionID$

channel $cleanUpCall : MissionID$
channel $cleanUpRet : MissionID \times \mathbb{B}$

channel $stowLandingGearCall : MissionID \times SchedulableID$
channel $stowLandingGearRet : MissionID \times SchedulableID$

channel $isLandingGearDeployedCall : MissionID \times SchedulableID$
channel $isLandingGearDeployedRet : MissionID \times SchedulableID \times \mathbb{B}$

channel $deployLandingGearCall : MissionID \times SchedulableID \times ThreadID$
channel $deployLandingGearRet : MissionID \times SchedulableID \times ThreadID$

5.4 Schedulables of TakeOffMission

section *LandingGearHandlerTakeOffApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*, *MethodCallBindingChannels* , *TakeOffMissionMethChan*, *ObjectIds*, *ThreadIds*

process $LandingGearHandlerTakeOffApp \mathrel{\widehat=}$
$mission : MissionID \bullet$ **begin**

$handleAsyncEvent \mathrel{\widehat=}$
$\Big($ $handleAsyncEventCall\,.\,LandingGearHandlerTakeOffSID \longrightarrow$
$\Big($ $binder\_isLandingGearDeployedCall\,.\,mission\,.\,LandingGearHandlerTakeOffSID \longrightarrow$
$binder\_isLandingGearDeployedRet\,.\,mission\,.\,LandingGearHandlerTakeOffSID$
$\quad ?\ isLandingGearDeployed \longrightarrow$
Skip
var $landingGearIsDeployed : \mathbb{B} \bullet landingGearIsDeployed := isLandingGearDeployed$;
if $landingGearIsDeployed =$ **True** $\longrightarrow$
$\quad \Big($ $binder\_stowLandingGearCall\,.\,mission\,.\,LandingGearHandlerTakeOffSID \longrightarrow$
$\quad\ binder\_stowLandingGearRet\,.\,mission\,.\,LandingGearHandlerTakeOffSID \longrightarrow$
$\quad\ $ **Skip** $\Big)$
$[]\ \neg\ landingGearIsDeployed =$ **True** $\longrightarrow$
$\quad \Big($ $binder\_deployLandingGearCall\,.\,mission\,.\,LandingGearHandlerTakeOffSID$
$\quad\quad .\ LandingGearHandlerTakeOffTID \longrightarrow$
$\quad\ binder\_deployLandingGearRet\,.\,mission\,.\,LandingGearHandlerTakeOffSID$
$\quad\quad .\ LandingGearHandlerTakeOffTID \longrightarrow$
$\quad\ $ **Skip** $\Big)$
fi $\Big)$
$handleAsyncEventRet\,.\,LandingGearHandlerTakeOffSID \longrightarrow$
Skip $\Big)$;

$Methods \mathrel{\widehat=}$
$\big(handleAsyncEvent\big)$; $Methods$

$\bullet\ (Methods) \triangle (end\_aperiodic\_app\,.\,LandingGearHandlerTakeOffSID \longrightarrow$ **Skip**$)$

end

section *TakeOffFailureHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*, *MethodCallBindingChannels*, *MainMissionMethChan*

process $TakeOffFailureHandlerApp \mathrel{\widehat=}$
$mainMission : MissionID, takeoffMission : MissionID, threshold : \mathbb{P}\,\mathbb{A} \bullet$ **begin**

$handleAsyncEvent \mathrel{\widehat=}$
$\Big($ $handleAsyncEventCall\,.\,TakeOffFailureHandlerSID \longrightarrow$
$\Big($ $binder\_getAirSpeedCall\,.\,mainMission\,.\,TakeOffFailureHandlerSID \longrightarrow$
$binder\_getAirSpeedRet\,.\,mainMission\,.\,TakeOffFailureHandlerSID\,?\,getAirSpeed \longrightarrow$
Skip var $currentSpeed : \mathbb{P}\,\mathbb{A} \bullet currentSpeed := getAirSpeed;$
if $(currentSpeed < threshold) \longrightarrow$
Skip
$[]\ \neg\,(currentSpeed < threshold) \longrightarrow$
Skip
fi
$\Big)$;
$handleAsyncEventRet\,.\,TakeOffFailureHandlerSID \longrightarrow$
Skip
$\Big)$

$Methods \mathrel{\widehat=}$
$\big(handleAsyncEvent\big)\ ;\ Methods$

$\bullet\ (Methods) \triangle (end\_aperiodic\_app\,.\,TakeOffFailureHandlerSID \longrightarrow$ **Skip**$)$

end

section *TakeOffFailureHandlerClass* **parents** *scj_prelude*, *SchedulableId*, *SchedulableIds*, *SafeletChan*, *MethodCallBindingChannels*

class *TakeOffFailureHandlerClass* $\widehat{=}$ **begin**

state *State*

$threshold : \mathbb{P}\,\mathbb{A}$

state *State*

initial *Init*

$State'$

- **Skip**

end

section *TakeOffMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*, *MethodCallBindingChannels*, *MainMissionMethChan*

process $TakeOffMonitorApp \mathrel{\widehat=}$
$mainMission : MissionID, takeOffMission : MissionID, takeOffAltitude : \mathbb{P}\,\mathbb{A},$
$landingGearHandler : SchedulableID \bullet$ **begin**

$$
\begin{pmatrix}
handleAsyncEventCall\,.\,TakeOffMonitorSID \longrightarrow \\
\left(\begin{array}{l}
binder\_getAltitudeCall\,.\,mainMission\,.\,TakeOffMonitorSID \longrightarrow \\
binder\_getAltitudeRet\,.\,mainMission\,.\,TakeOffMonitorSID\,?\,getAltitude \longrightarrow \\
\textbf{Skip var } altitude : \mathbb{P}\,\mathbb{A} \bullet altitude := getAltitude; \\
\textbf{if } (altitude > takeOffAltitude) \longrightarrow \\
\quad \textbf{Skip} \\
[]\ \neg\,(altitude > takeOffAltitude) \longrightarrow \textbf{Skip} \\
\textbf{fi}
\end{array}\right); \\
handleAsyncEventRet\,.\,TakeOffMonitorSID \longrightarrow \\
\textbf{Skip}
\end{pmatrix}
$$

$Methods \mathrel{\widehat=}$
$\big(handleAsyncEvent\big)\ ;\ Methods$

$\bullet\ (Methods) \triangle (end\_periodic\_app\,.\,TakeOffMonitorSID \longrightarrow \textbf{Skip})$

end

section *TakeOffMonitorClass* **parents** *scj_prelude*, *SchedulableId*, *SchedulableIds*, *SafeletChan*
, *MethodCallBindingChannels*

class *TakeOffMonitorClass* $\widehat{=}$ **begin**

state *State*

$takeoffMission : TakeOffMission$
$takeOffAltitude : \mathbb{P}\,\mathbb{A}$

state *State*

initial *Init*

$State'$

- **Skip**

end

5.5 CruiseMission

section *CruiseMissionApp* **parents** *scj_prelude*, *MissionId*, *MissionIds*, *SchedulableId*, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *CruiseMissionMethChan*, *MethodCallBindingChannels*

process $CruiseMissionApp \mathrel{\widehat=}$
$controllingMission : MissionID \bullet$ **begin**

State

$this : \mathbf{ref}\ CruiseMissionClass$

state *State*

Init

$State'$

$this' = \mathbf{new}\ CruiseMissionClass()$

$$InitializePhase \mathrel{\widehat=} \begin{pmatrix} initializeCall\,.\,CruiseMissionMID \longrightarrow \\ register\,!\,BeginLandingHandlerSID\,!\,CruiseMissionMID \longrightarrow \\ register\,!\,NavigationMonitorSID\,!\,CruiseMissionMID \longrightarrow \\ initializeRet\,.\,CruiseMissionMID \longrightarrow \\ \mathbf{Skip} \end{pmatrix}$$

$$CleanupPhase \mathrel{\widehat=} \begin{pmatrix} cleanupMissionCall\,.\,CruiseMissionMID \longrightarrow \\ cleanupMissionRet\,.\,CruiseMissionMID\,!\,\mathbf{True} \longrightarrow \\ \mathbf{Skip} \end{pmatrix}$$

$$Methods \mathrel{\widehat=} \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} ;\ Methods$$

$$\bullet\ (Init\ ;\ Methods) \triangle (end\_mission\_app\,.\,CruiseMissionMID \longrightarrow \mathbf{Skip})$$

end

section *CruiseMissionClass* **parents** *scj_prelude*, *SchedulableId*, *SchedulableIds*, *SafeletChan*
, *MethodCallBindingChannels*

class *CruiseMissionClass* $\widehat{=}$ **begin**

state *State*

$controllingMission : MainMission$

state *State*

initial *Init*

$State'$

• **Skip**

end

5.6 Schedulables of CruiseMission

section *BeginLandingHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*, *MethodCallBindingChannels*

process $BeginLandingHandlerApp \mathrel{\widehat=}$
$controllingMission : MissionID \bullet$ **begin**

$handleAsyncEvent \mathrel{\widehat=}$
$\left(\begin{array}{l} handleAsyncEventCall\,.\,BeginLandingHandlerSID \longrightarrow \\ \textbf{Skip}; \\ handleAsyncEventRet\,.\,BeginLandingHandlerSID \longrightarrow \\ \textbf{Skip} \end{array}\right)$

$Methods \mathrel{\widehat=}$
$\big(handleAsyncEvent\big)\ ;\ Methods$

$\bullet\ (Methods) \triangle (end\_aperiodic\_app\,.\,BeginLandingHandlerSID \longrightarrow \textbf{Skip})$

end

section *NavigationMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*, *MethodCallBindingChannels*, *MainMissionMethChan*

process $NavigationMonitorApp \mathrel{\widehat=}$
$mainMission : MissionID \bullet$ **begin**

$handleAsyncEvent \mathrel{\widehat=}$
$\Big(handleAsyncEventCall\,.\,NavigationMonitorSID \longrightarrow$
$\quad \Big(binder\_getHeadingCall\,.\,mainMission\,.\,NavigationMonitorSID \longrightarrow$
$\quad\; binder\_getHeadingRet\,.\,mainMission\,.\,NavigationMonitorSID\,?\,getHeading \longrightarrow$
$\quad\; \mathbf{Skip}\ \mathbf{var}\ heading : \mathbb{P}\,\mathbb{A} \bullet heading := getHeading;$
$\quad\; binder\_getAirSpeedCall\,.\,mainMission\,.\,NavigationMonitorSID \longrightarrow$
$\quad\; binder\_getAirSpeedRet\,.\,mainMission\,.\,NavigationMonitorSID\,?\,getAirSpeed \longrightarrow$
$\quad\; \mathbf{Skip}\ \mathbf{var}\ airSpeed : \mathbb{P}\,\mathbb{A} \bullet airSpeed := getAirSpeed;$
$\quad\; binder\_getAltitudeCall\,.\,mainMission\,.\,NavigationMonitorSID \longrightarrow$
$\quad\; binder\_getAltitudeRet\,.\,mainMission\,.\,NavigationMonitorSID\,?\,getAltitude \longrightarrow$
$\quad\; \mathbf{Skip}\ \mathbf{var}\ altitude : \mathbb{P}\,\mathbb{A} \bullet altitude := getAltitude \Big)$
$handleAsyncEventRet\,.\,NavigationMonitorSID \longrightarrow$
$\mathbf{Skip} \Big)$

$Methods \mathrel{\widehat=}$
$\big(handleAsyncEvent \big)\ ;\ Methods$

$\bullet\ (Methods) \triangle (end\_periodic\_app\,.\,NavigationMonitorSID \longrightarrow \mathbf{Skip})$

end

5.7 LandMission

section *LandMissionApp* **parents** *scj_prelude*, *MissionId*, *MissionIds*, *SchedulableId*, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *LandMissionMethChan*, *LandMissionClass*, *MethodCallBindingChannels*, *ObjectFWChan*, *ObjectIds*

process $LandMissionApp \mathrel{\widehat=}$
$controllingMission : MissionID \bullet$ **begin**

State

$this : \mathbf{ref}\ LandMissionClass$

state *State*

Init

$State'$

$this' = \mathbf{new}\ LandMissionClass()$

$InitializePhase \mathrel{\widehat=}$
$\left(\begin{array}{l} initializeCall\,.\,LandMissionMID \longrightarrow \\ register\,!\,GroundDistanceMonitorSID\,!\,LandMissionMID \longrightarrow \\ register\,!\,LandingGearHandlerLandSID\,!\,LandMissionMID \longrightarrow \\ register\,!\,InstrumentLandingSystemMonitorSID\,!\,LandMissionMID \longrightarrow \\ register\,!\,SafeLandingHandlerSID\,!\,LandMissionMID \longrightarrow \\ initializeRet\,.\,LandMissionMID \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$CleanupPhase \mathrel{\widehat=}$
$\left(\begin{array}{l} cleanupMissionCall\,.\,LandMissionMID \longrightarrow \\ cleanupMissionRet\,.\,LandMissionMID\,!\,\mathbf{True} \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$stowLandingGearMeth \mathrel{\widehat=}$
$\left(\begin{array}{l} stowLandingGearCall\,.\,LandMissionMID\,?\,caller \longrightarrow \\ this\,.\,stowLandingGear(); \\ stowLandingGearRet\,.\,LandMissionMID\,.\,caller \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$isLandingGearDeployedMeth \mathrel{\widehat=} \mathbf{var}\ ret : \mathbb{B} \bullet$
$\left(\begin{array}{l} isLandingGearDeployedCall\,.\,LandMissionMID\,?\,caller \longrightarrow \\ ret := this\,.\,isLandingGearDeployed(); \\ isLandingGearDeployedRet\,.\,LandMissionMID\,.\,caller\,!\,ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$cleanUpMeth \mathrel{\widehat=} \mathbf{var}\ ret : \mathbb{B} \bullet$
$\left(\begin{array}{l} cleanUpCall\,.\,LandMissionMID \longrightarrow \\ ret := this\,.\,cleanUp(); \\ cleanUpRet\,.\,LandMissionMID\,!\,ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$$
\begin{array}{l}
deployLandingGearSyncMeth \mathrel{\widehat{=}} \\
\left(\begin{array}{l}
deployLandingGearCall\,.\,LandMissionMID\,?\,caller\,?\,thread \longrightarrow \\
\left(\begin{array}{l}
startSyncMeth\,.\,LandMissionOID\,.\,thread \longrightarrow \\
lockAcquired\,.\,LandMissionOID\,.\,thread \longrightarrow \\
\big(this\,.\,landingGearDeployed := \mathbf{True}\big)\,; \\
endSyncMeth\,.\,LandMissionOID\,.\,thread \longrightarrow \\
deployLandingGearRet\,.\,LandMissionMID\,.\,caller\,.\,thread \longrightarrow \\
\mathbf{Skip}
\end{array}\right)
\end{array}\right)
\end{array}
$$

$$
Methods \mathrel{\widehat{=}} \left(\begin{array}{l}
InitializePhase \\
\Box \\
CleanupPhase \\
\Box \\
stowLandingGearMeth \\
\Box \\
isLandingGearDeployedMeth \\
\Box \\
cleanUpMeth \\
\Box \\
deployLandingGearSyncMeth
\end{array}\right)\ ;\ Methods
$$

$\bullet\ (Init\ ;\ \ Methods) \triangle (end\_mission\_app\,.\,LandMissionMID \longrightarrow \mathbf{Skip})$

end

section *LandMissionClass* **parents** *scj_prelude*, *SchedulableId*, *SchedulableIds*, *SafeletChan*
, *MethodCallBindingChannels*

class *LandMissionClass* $\widehat{=}$ **begin**

state *State*

$$controllingMission : MainMission$$
$$SAFE\_LANDING\_ALTITUDE : \mathbb{P}\,\mathbb{A}$$
$$abort : \mathbb{B}$$
$$landingGearDeployed : \mathbb{B}$$

state *State*

initial *Init*

$$State'$$

public *stowLandingGear* $\widehat{=}$
$\big(this\,.\,landingGearDeployed := \mathbf{False}\big)$

public *isLandingGearDeployed* $\widehat{=}$ **var** $ret : \mathbb{B} \bullet$
$\big(ret := landingGearDeployed = \mathbf{True}\big)$

public *cleanUp* $\widehat{=}$ **var** $ret : \mathbb{B} \bullet$
$\big(ret := \mathbf{False}\big)$

• **Skip**

end

section *LandMissionMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

channel *stowLandingGearCall* : *MissionID*×
channel *stowLandingGearRet* : *MissionID*×

channel *isLandingGearDeployedCall* : *MissionID*×
channel *isLandingGearDeployedRet* : *MissionID* × ×$\mathbb{B}$

channel *cleanUpCall* : *MissionID*
channel *cleanUpRet* : *MissionID* × $\mathbb{B}$

channel *deployLandingGearCall* : *MissionID* × × *ThreadID*
channel *deployLandingGearRet* : *MissionID* × × *ThreadID*

5.8 Schedulables of LandMission

section *LandingGearHandlerLandApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*, *MethodCallBindingChannels*, *LandMissionMethChan*, *ObjectIds*, *ThreadIds*

process $LandingGearHandlerLandApp \mathrel{\widehat=}$
$mission : MissionID \bullet$ **begin**

$handleAsyncEvent \mathrel{\widehat=}$
$\Big($ *handleAsyncEventCall . LandingGearHandlerLandSID* $\longrightarrow$
$\Big($ *binder_isLandingGearDeployedCall . mission . LandingGearHandlerLandSID* $\longrightarrow$
binder_isLandingGearDeployedRet . mission . LandingGearHandlerLandSID ? *isLandingGearDeployed* $\longrightarrow$
Skip var $landingGearIsDeployed : \mathbb{B} \bullet landingGearIsDeployed := isLandingGearDeployed$;
if $landingGearIsDeployed = \mathbf{True} \longrightarrow$
$\Big($ *binder_stowLandingGearCall . mission*
. LandingGearHandlerLandSID $\longrightarrow$
binder_stowLandingGearRet . mission
. LandingGearHandlerLandSID $\longrightarrow$
Skip $\Big)$
$[] \neg landingGearIsDeployed = \mathbf{True} \longrightarrow$
$\Big($ *binder_deployLandingGearCall . mission . LandingGearHandlerLandSID*
. LandingGearHandlerLandTID $\longrightarrow$
binder_deployLandingGearRet . mission . LandingGearHandlerLandSID
. LandingGearHandlerLandTID $\longrightarrow$
Skip $\Big)$
fi $\Big)$;
handleAsyncEventRet . LandingGearHandlerLandSID $\longrightarrow$
Skip $\Big)$

$Methods \mathrel{\widehat=}$
$\big($ *handleAsyncEvent* $\big)$; $Methods$

$\bullet$ $(Methods) \triangle (end\_aperiodic\_app\ .\ LandingGearHandlerLandSID \longrightarrow \mathbf{Skip})$

end

section *SafeLandingHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*, *MethodCallBindingChannels*, *MainMissionMethChan*

process $SafeLandingHandlerApp \mathrel{\widehat=}$
$\quad mainMission : MissionID,$
$threshold : \mathbb{P}\,\mathbb{A} \bullet$ **begin**

$handleAsyncEvent \mathrel{\widehat=}$
$\Big($ $handleAsyncEventCall\,.\,SafeLandingHandlerSID \longrightarrow$
$\quad \Big($ $binder\_getAltitudeCall\,.\,mainMission\,.\,SafeLandingHandlerSID \longrightarrow$
$\quad\; binder\_getAltitudeRet\,.\,mainMission\,.\,SafeLandingHandlerSID\,?\,getAltitude \longrightarrow$
$\quad\; \mathbf{Skip}\ \mathbf{var}\ altitude : \mathbb{P}\,\mathbb{A} \bullet altitude := getAltitude;$
$\quad\; \mathbf{if}\ (altitude < threshold) \longrightarrow$
$\quad\quad \mathbf{Skip}$
$\quad\; [] \neg\,(altitude < threshold) \longrightarrow$
$\quad\quad \mathbf{Skip}$
$\quad\; \mathbf{fi}$
$\quad \Big)$;
$\quad handleAsyncEventRet\,.\,SafeLandingHandlerSID \longrightarrow$
$\quad \mathbf{Skip}$
$\Big)$

$Methods \mathrel{\widehat=}$
$\big(handleAsyncEvent\big)\ ;\ Methods$

$\bullet\ (Methods) \triangle (end\_aperiodic\_app\,.\,SafeLandingHandlerSID \longrightarrow \mathbf{Skip})$

end

section *SafeLandingHandlerClass* **parents** *scj_prelude*, *SchedulableId*, *SchedulableIds*, *SafeletChan*, *MethodCallBindingChannels*

class *SafeLandingHandlerClass* $\widehat{=}$ **begin**

state *State*

$threshold : \mathbb{P}\,\mathbb{A}$

state *State*

initial *Init*

$State'$

- **Skip**

end

section *GroundDistanceMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*, *MethodCallBindingChannels*, *MainMissionMethChan*

process $GroundDistanceMonitorApp \mathrel{\widehat=}$
$mainMission : MissionID \bullet$ **begin**

$handleAsyncEvent \mathrel{\widehat=}$
$\Big(handleAsyncEventCall\,.\,GroundDistanceMonitorSID \longrightarrow$
$\quad \Big(binder\_getAltitudeCall\,.\,mainMission\,.\,GroundDistanceMonitorSID \longrightarrow$
$\quad\; binder\_getAltitudeRet\,.\,mainMission\,.\,GroundDistanceMonitorSID\,?\,getAltitude \longrightarrow$
$\quad\; \mathbf{Skip}\ \mathbf{var}\ distance : \mathbb{P}\,\mathbb{A} \bullet distance := getAltitude;$
$\quad\; \mathbf{if}\ (distance = readingOnGround) \longrightarrow$
$\quad\quad\; \mathbf{Skip}$
$\quad\; [\!] \neg\,(distance = readingOnGround) \longrightarrow \mathbf{Skip}$
$\quad\; \mathbf{fi} \Big)$
$\quad handleAsyncEventRet\,.\,GroundDistanceMonitorSID \longrightarrow$
$\quad \mathbf{Skip} \Big)$
$;$

$Methods \mathrel{\widehat=}$
$\big(handleAsyncEvent \big)\ ;\ Methods$

$\bullet\ (Methods) \triangle (end\_periodic\_app\,.\,GroundDistanceMonitorSID \longrightarrow \mathbf{Skip})$

end

section *GroundDistanceMonitorClass* **parents** *scj_prelude*, *SchedulableId*, *SchedulableIds*, *SafeletChan*, *MethodCallBindingChannels*

class *GroundDistanceMonitorClass* $\widehat{=}$ **begin**

state *State*

$readingOnGround : \mathbb{P}\,\mathbb{A}$

state *State*

initial *Init*

$State'$

- **Skip**

end

section *InstrumentLandingSystemMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*, *MethodCallBindingChannels*

process *InstrumentLandingSystemMonitorApp* $\widehat{=}$
mission : *MissionID* • **begin**

$$
\begin{pmatrix}
\textit{handleAsyncEventCall} \,.\, \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \\
\textbf{Skip}; \\
\textit{handleAsyncEventRet} \,.\, \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \\
\textbf{Skip}
\end{pmatrix}
$$

$$
\begin{pmatrix}
\textit{handleAsyncEvent}
\end{pmatrix} ; \; \textit{Methods}
$$

$$
\bullet \; (\textit{Methods}) \triangle (\textit{end\_periodic\_app} \,.\, \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \textbf{Skip})
$$

end